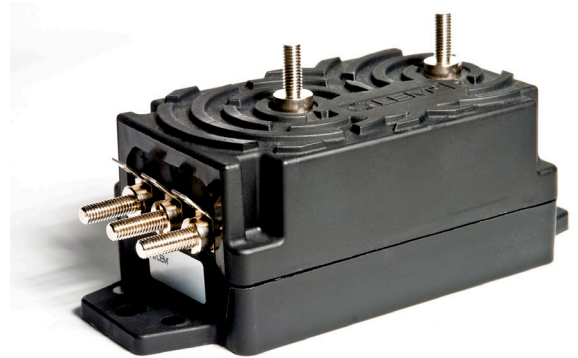


## Voltage transducer DVL 1000

$$U_{PN} = 1000 \text{ V}$$

For the electronic measurement of voltage: DC, AC, pulsed..., with galvanic separation between the primary and the secondary circuit.



### Features

- Bipolar and insulated measurement up to 1500 V
- Current output
- Input and output connections with M5 studs
- Compatible with AV 100 family.

### Advantages

- Low consumption and low losses
- Compact design
- Good behavior under common mode variations
- Excellent accuracy (offset, sensitivity, linearity)
- Good delay time
- Low temperature variation
- High immunity to external interferences.

### Applications

- AC variable speed and servo motor drives
- Static converters for DC motor drives
- Battery supplied applications
- Uninterruptible Power Supplies (UPS)
- Switched Mode Power Supplies (SMPS)
- Power supplies for welding applications
- Renewable Energy (Solar and Wind)
- Single or three phase inverters
- Propulsion and braking choppers
- Propulsion converters
- Auxiliary converters
- High power drives
- Substations.

### Standards

- EN 50155: 2021
- EN 50178: 1997
- EN 50124-1: 2017
- EN 50121-3-2: 2016
- UL 508: 2013.

### Application Domains

- Railway (fixed installations and onboard)
- Industrial.

## Absolute maximum ratings

**DVL 1000**

Parameter	Symbol	Unit	Value
Maximum supply voltage ( $U_p = 0 \text{ V}$ , 0.1 s)	$\pm U_{C \text{ max}}$	V	$\pm 34$
Maximum supply voltage (working) ( $-40 \dots 85 \text{ }^\circ\text{C}$ )	$\pm U_{C \text{ max}}$	V	$\pm 26.4$
Maximum input voltage ( $-40 \dots 85 \text{ }^\circ\text{C}$ )	$U_{P \text{ max}}$	V	1500
Maximum steady state input voltage ( $-40 \dots 85 \text{ }^\circ\text{C}$ )	$U_{P \text{ N max}}$	V	1000 see derating on <a href="#">figure 2</a>

Absolute maximum ratings apply at  $25 \text{ }^\circ\text{C}$  unless otherwise noted.

Stresses above these ratings may cause permanent damage.

Exposure to absolute maximum ratings for extended periods may degrade reliability.

## UL 508: Ratings and assumptions of certification

File # E189713 Volume: 2 Section: 7

### Standards

- USR indicated investigation to the Standard for Industrial Control Equipment UL 508.
- CNR Indicated investigation to the Canadian standard for Industrial Control Equipment CSA C22.2 No. 14-13

### Conditions of acceptability

When installed in the end-use equipment, consideration shall be given to the following:

- 1 - *These devices must be mounted in a suitable end-use enclosure.*
- 2 - *The terminal have not been evaluated for field wiring.*
- 3 - *Low voltage circuits are intended to be powered by a circuit derived from an isolating source (such as transformer, optical isolator, limiting impedance or electro-mechanical relay) and having no direct connection back to the primary circuit (other than through the grounding means).*

### Marking

Only those products bearing the UL or UR Mark should be considered to be Listed or Recognized and covered under UL's Follow-Up Service. Always look for the Mark on the product.

## Insulation coordination

Parameter	Symbol	Unit	Value	Comment
RMS voltage for AC insulation test, 50 Hz, 1 min	$U_d$	kV	8.5	100 % tested in production
Impulse withstand voltage 1.2/50 $\mu$ s	$U_{Ni}$	kV	16	
Partial discharge RMS test voltage ( $q_m < 10$ pC)	$U_t$	V	2700	
Insulation resistance	$R_{INS}$	M $\Omega$	200	Measured at 500 V DC
Clearance (pri. - sec.)	$d_{Cl}$	mm	See dimensions drawing on <a href="#">page 9</a>	Shortest distance through air
Creepage distance (pri. - sec.)	$d_{Cp}$	mm		Shortest path along device body
Case material	-	-	V0	According to UL 94
Comparative tracking index	$CTI$		600	
Maximum DC common mode voltage	$U_{HV+} + U_{HV-}$ and $ U_{HV+} - U_{HV-} $	kV	$\leq 4.2$ $\leq U_{PM}$	

## Environmental and mechanical characteristics

Parameter	Symbol	Unit	Min	Typ	Max
Ambient operating temperature	$T_A$	°C	-40		85
Ambient storage temperature	$T_{Ast}$	°C	-50		90
Equipment operating temperature class					EN 50155: OT6
Switch-on extended operating temperature class					EN 50155: ST0
Rapid temperature variation class					EN 50155: H2
Conformal coating type					EN 50155: PC2
Mass	$m$	g		290	

## RAMS data

Parameter	Symbol	Unit	Min	Typ	Max
Useful life class					EN 50155: L4
Mean failure rate	$\lambda$	$h^{-1}$		1/1835004	According to IEC 62380: 2004 $T_A = 45$ °C ON: 20 hrs/day ON/OFF: 320 cycles/year $U_C = \pm 24$ V, $U_P = 1000$ V

## Electrical data

At  $T_A = 25\text{ °C}$ ,  $\pm U_C = \pm 24\text{ V}$ ,  $R_M = 100\text{ }\Omega$ , unless otherwise noted.

Lines with a \* in the conditions column apply over the  $-40 \dots 85\text{ °C}$  ambient temperature range.

Parameter	Symbol	Unit	Min	Typ	Max	Conditions
Primary nominal RMS voltage	$U_{PN}$	V		1000		*
Primary voltage, measuring range	$U_{PM}$	V	-1500		1500	*
Measuring resistance	$R_M$	$\Omega$	0		133	* See derating on <a href="#">figure 2</a> . For $ U_{PM}  < 1500\text{ V}$ , max value of $R_M$ is given on <a href="#">figure 1</a>
Secondary nominal RMS current	$I_{SN}$	mA		50		*
Secondary current	$I_S$	mA	-75		75	*
Supply voltage	$\pm U_C$	V	$\pm 13.5$	$\pm 24$	$\pm 26.4$	*
Rise time of $U_C$ (10 – 90 %)	$t_{rise}$	ms			100	
Current consumption @ $U_C = \pm 24\text{ V}$ at $U_P = 0\text{ V}$	$I_C$	mA		20	25	
Inrush current						NA (EN 50155)
Interruptions on power supply voltage class						NA (EN 50155)
Supply change-over class						NA (EN 50155)
Offset current	$I_O$	$\mu\text{A}$	-50	0	50	100 % tested in production
Temperature variation of $I_O$	$I_{OT}$	$\mu\text{A}$	-120 -150		120 150	-25 ... 85 °C -40 ... 85 °C
Sensitivity	$S$	$\mu\text{A/V}$		50		50 mA for primary 1000 V
Sensitivity error	$\varepsilon_S$	%	-0.2	0	0.2	
Temperature variation of sensitivity error	$\varepsilon_{ST}$	%	-0.5		0.5	* Referred to 25 °C
Linearity error	$\varepsilon_L$	% of $U_{PM}$	-0.5		0.5	*
Total error	$\varepsilon_{tot}$	% of $U_{PN}$	-0.5 -1		0.5 1	* 25 °C; 100 % tested in production -40 ... 85 °C
RMS noise current referred to primary	$I_{no}$	$\mu\text{A}$		10		1 Hz to 100 kHz
Delay time @ 10 % of the final output value $U_{PN\text{ step}}$	$t_{D10}$	$\mu\text{s}$		30		
Delay time @ 90 % of the final output value $U_{PN\text{ step}}$	$t_{D90}$	$\mu\text{s}$		50	60	0 to 1000 V step, 6 kV/ $\mu\text{s}$
Frequency bandwidth	$BW$	kHz		14 8 2		-3 dB -1 dB -0.1 dB
Start-up time	$t_{start}$	ms		190	250	*
Resistance of primary (winding)	$R_P$	M $\Omega$		11.3		*
Total primary power loss @ $U_{PN}$	$P_P$	mW		0.09		*

## Definition of typical, minimum and maximum values

Minimum and maximum values for specified limiting and safety conditions have to be understood as such as well as values shown in “typical” graphs.

On the other hand, measured values are part of a statistical distribution that can be specified by an interval with upper and lower limits and a probability for measured values to lie within this interval.

Unless otherwise stated (e.g. “100 % tested”), the LEM definition for such intervals designated with “min” and “max” is that the probability for values of samples to lie in this interval is 99.73 %.

For a normal (Gaussian) distribution, this corresponds to an interval between -3 sigma and +3 sigma. If “typical” values are not obviously mean or average values, those values are defined to delimit intervals with a probability of 68.27 %, corresponding to an interval between -sigma and +sigma for a normal distribution.

Typical, maximal and minimal values are determined during the initial characterization of a product.

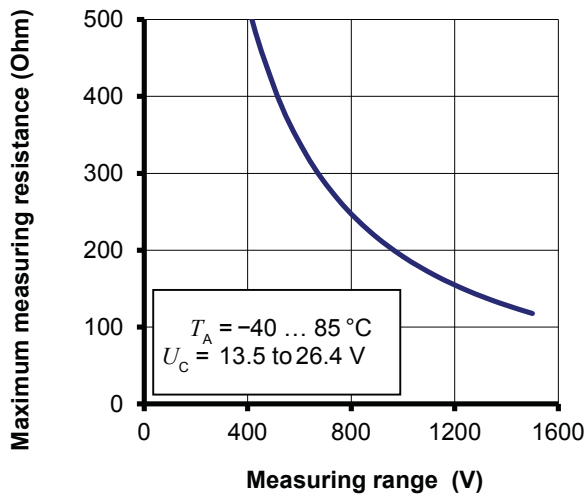


Figure 1: Maximum measuring resistance

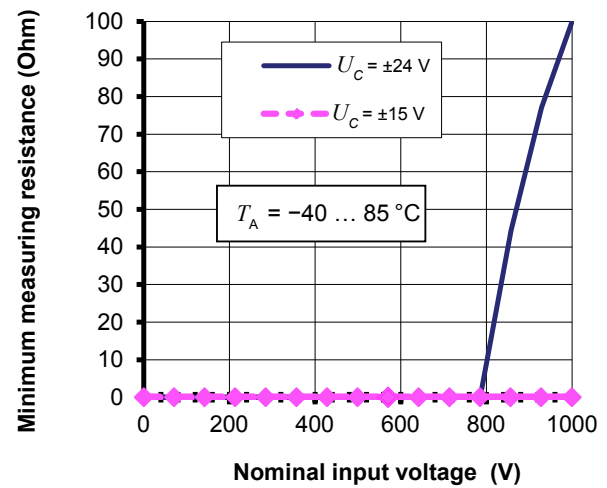


Figure 2: Minimum measuring resistance  
The derating @  $\pm 24 \text{ V}$  is only applicable for  $T_A = 80 \dots 85 \text{ }^\circ\text{C}$   
For  $T_A$  under  $80 \text{ }^\circ\text{C}$ , the minimum measuring resistance is  $0 \text{ } \Omega$  whatever  $U_C$

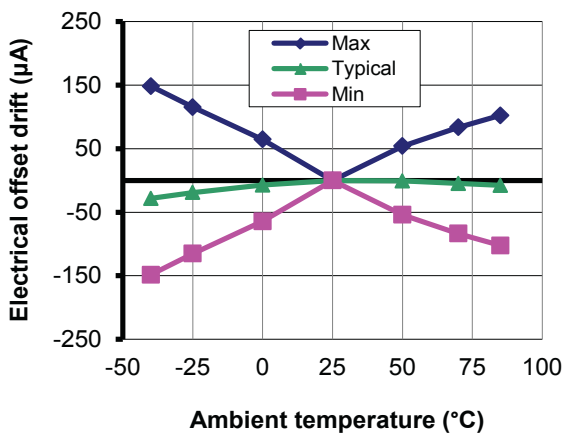


Figure 3: Electrical offset thermal drift

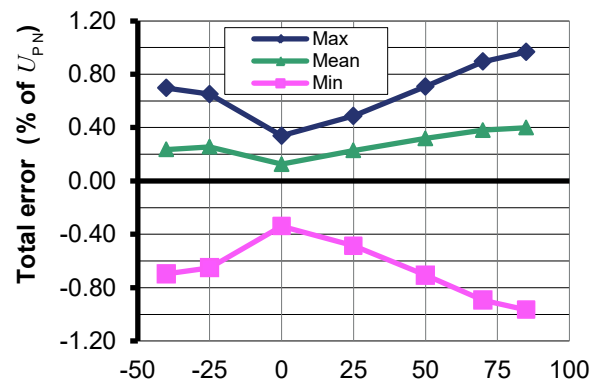


Figure 4: Total error in temperature

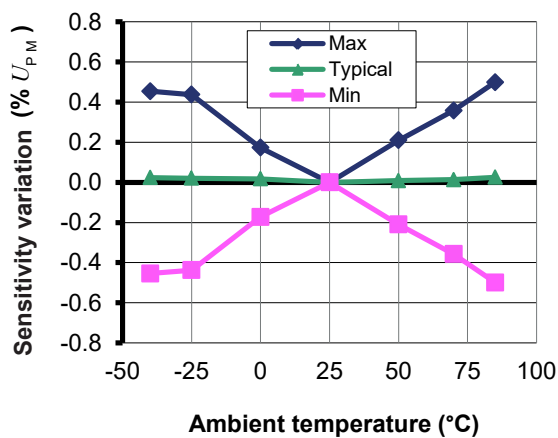


Figure 5: Sensitivity thermal variation

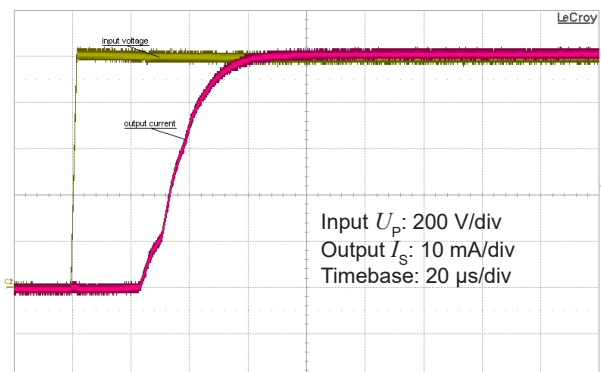


Figure 6: Typical step response (0 to 1000 V)

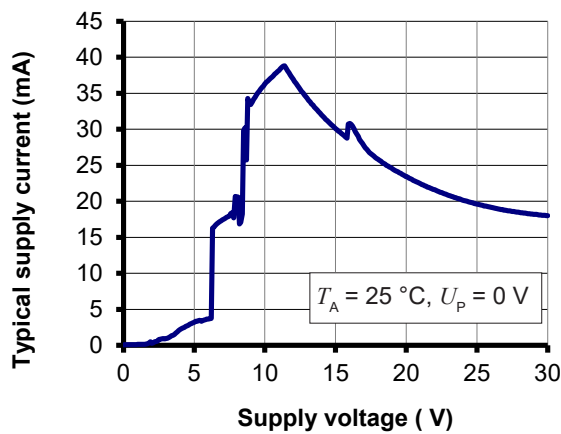


Figure 7: Supply current function of supply voltage

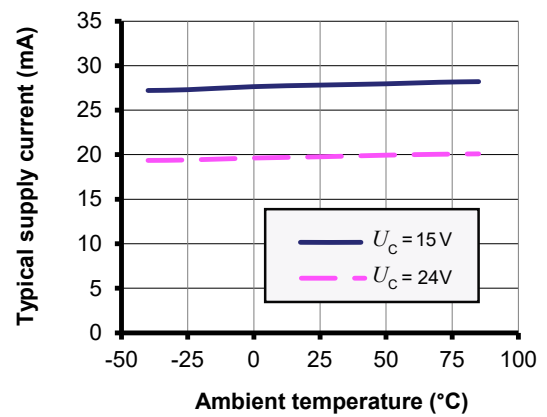
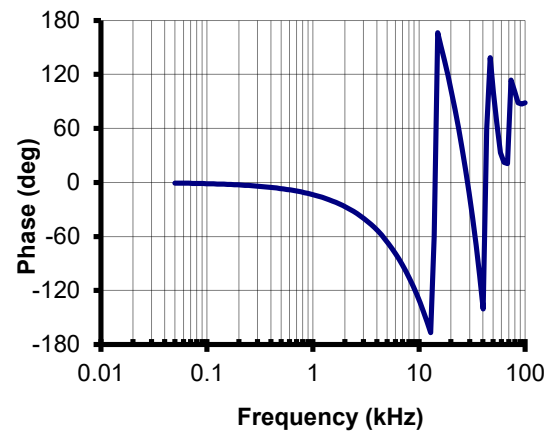
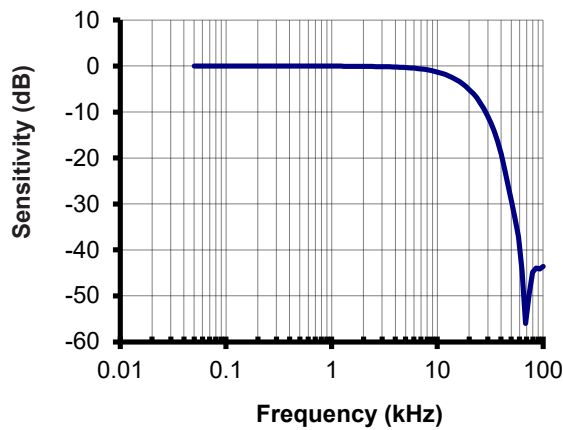
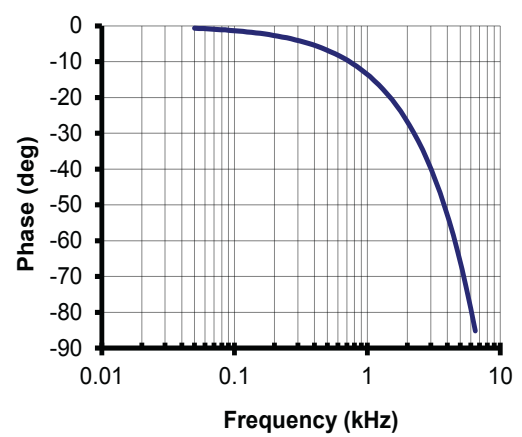
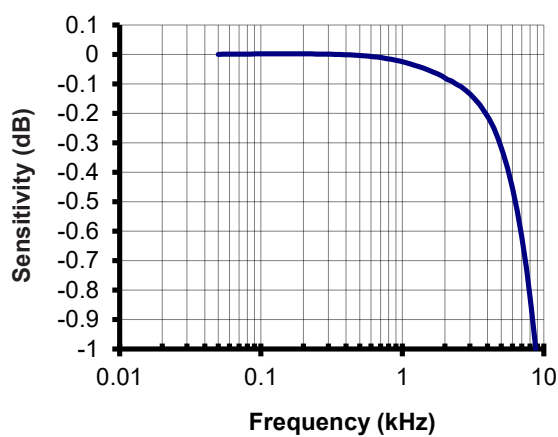


Figure 8: Supply current function of temperature



Figures 9 and 10: Typical frequency and phase response



Figures 11 and 12: Typical frequency and phase response (detail)

## Typical performance characteristics continued

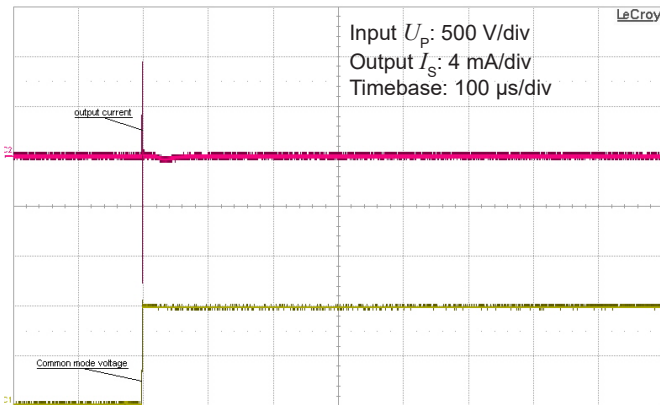


Figure 13: Typical common mode perturbation  
(1000 V step with 6 kV/μs,  $R_M = 100 \Omega$ )

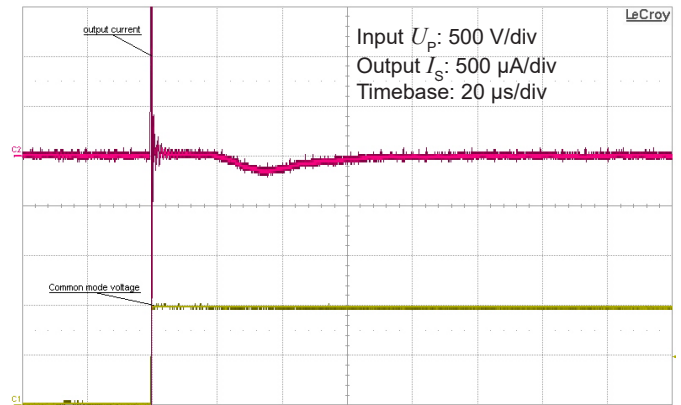


Figure 14: Detail of typical common mode perturbation  
(1000 V step with 6 kV/μs,  $R_M = 100 \Omega$ )

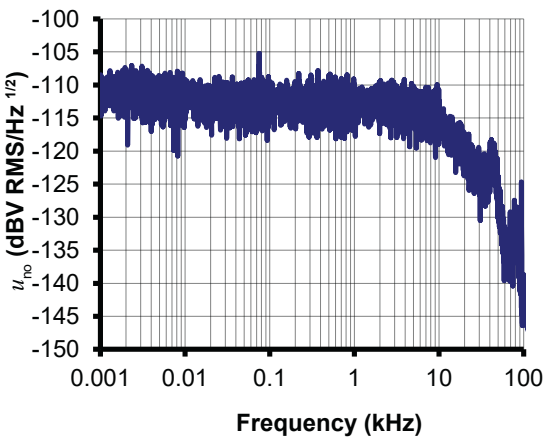


Figure 15: Typical noise voltage spectral density  
 $u_{no}$  with  $R_M = 50 \Omega$

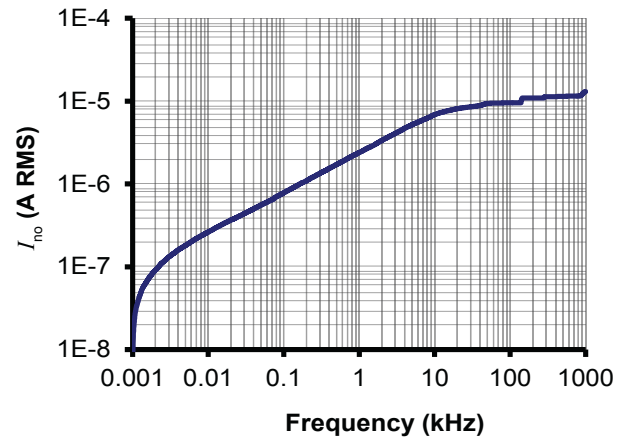


Figure 16: Typical total output RMS noise current  
with  $R_M = 50 \Omega$

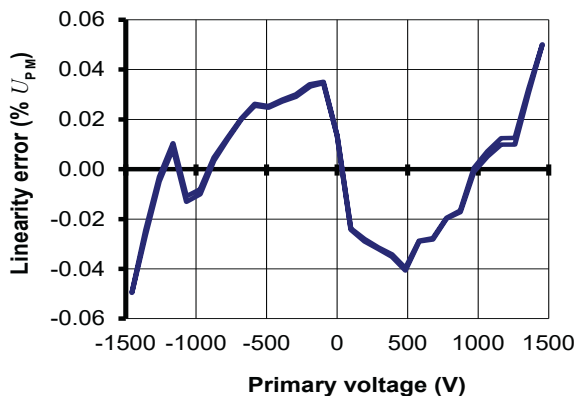


Figure 17: Typical linearity error at 25 °C

Figure 15 (noise voltage spectral density) shows that there are no significant discrete frequencies in the output. Figure 16 confirms the absence of steps in the total output RMS noise current that would indicate discrete frequencies. To calculate the noise in a frequency band  $f_1$  to  $f_2$ , the formula is:

$$I_{no}(f_1 \text{ to } f_2) = \sqrt{I_{no}(f_2)^2 - I_{no}(f_1)^2}$$

with  $I_{no}(f)$  read from figure 16 (typical, RMS value).

Example:

What is the noise from 10 to 100 Hz?

Figure 16 gives  $I_{no}(10 \text{ Hz}) = 0.26 \mu\text{A}$

and  $I_{no}(100 \text{ Hz}) = 0.8 \mu\text{A}$ .

The output RMS noise current is therefore.

$$\sqrt{(0.8 \times 10^{-6})^2 - (0.26 \times 10^{-6})^2} = 0.76 \mu\text{A}$$

The schematic used to measure all electrical parameters are:

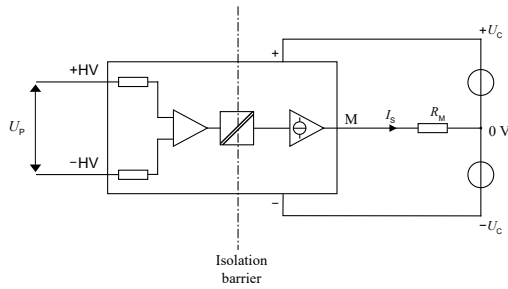


Figure 18: Standard characterization schematics for current output transducers ( $R_M = 50 \Omega$  unless otherwise noted)

### Transducer simplified model

The static model of the transducer at temperature  $T_A$  is:

$$I_s = S \cdot U_P + \varepsilon$$

In which

$$\varepsilon = I_{OE} + I_{OT}(T_A) + \varepsilon_S \cdot S \cdot U_P + \varepsilon_{ST}(T_A) \cdot S \cdot U_P + \varepsilon_L \cdot S \cdot U_{PM}$$

- $I_s$  : secondary current (A)
- $S$  : sensitivity of the transducer ( $\mu A/V$ )
- $U_P$  : primary voltage (V)
- $U_{PM}$  : primary voltage, measuring range (V)
- $T_A$  : ambient operating temperature ( $^{\circ}C$ )
- $I_{OE}$  : electrical offset current (A)
- $I_{OT}(T_A)$  : temperature variation of  $I_{OE}$  at temperature  $T_A$  (A)
- $\varepsilon_S$  : sensitivity error at  $25^{\circ}C$
- $\varepsilon_{ST}(T_A)$  : temperature variation of sensitivity error at temperature  $T_A$
- $\varepsilon_L$  : linearity error

This is the absolute maximum error. As all errors are independent, a more realistic way to calculate the error would be to use the following formula:

$$\varepsilon = \sqrt{\sum_{i=1}^N \varepsilon_i^2}$$

### Sensitivity and linearity

To measure sensitivity and linearity, the primary voltage (DC) is cycled from 0 to  $U_{PM}$ , then to  $-U_{PM}$  and back to 0 (equally spaced  $U_{PM}/10$  steps).

The sensitivity  $S$  is defined as the slope of the linear regression line for a cycle between  $\pm U_{PM}$ .

The linearity error  $\varepsilon_L$  is the maximum positive or negative difference between the measured points and the linear regression line, expressed in % of the maximum measured value.

### Electrical offset

The electrical offset current  $I_{OE}$  is the residual output current when the input voltage is zero.

The temperature variation  $I_{OT}$  of the electrical offset current  $I_{OE}$  is the variation of the electrical offset from  $25^{\circ}C$  to the considered temperature.

### Total error

The total error  $\varepsilon_{tot}$  is the error at  $\pm U_{PN}$ , relative to the rated value  $U_{PN}$ .

It includes all errors mentioned above.

### Delay times

The delay time  $t_{D10}$  and the delay time  $t_{D90}$  are shown in the next figure.

Both depend on the primary voltage  $dV/dt$ . They are measured at nominal voltage.

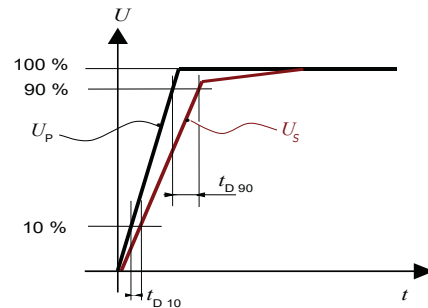
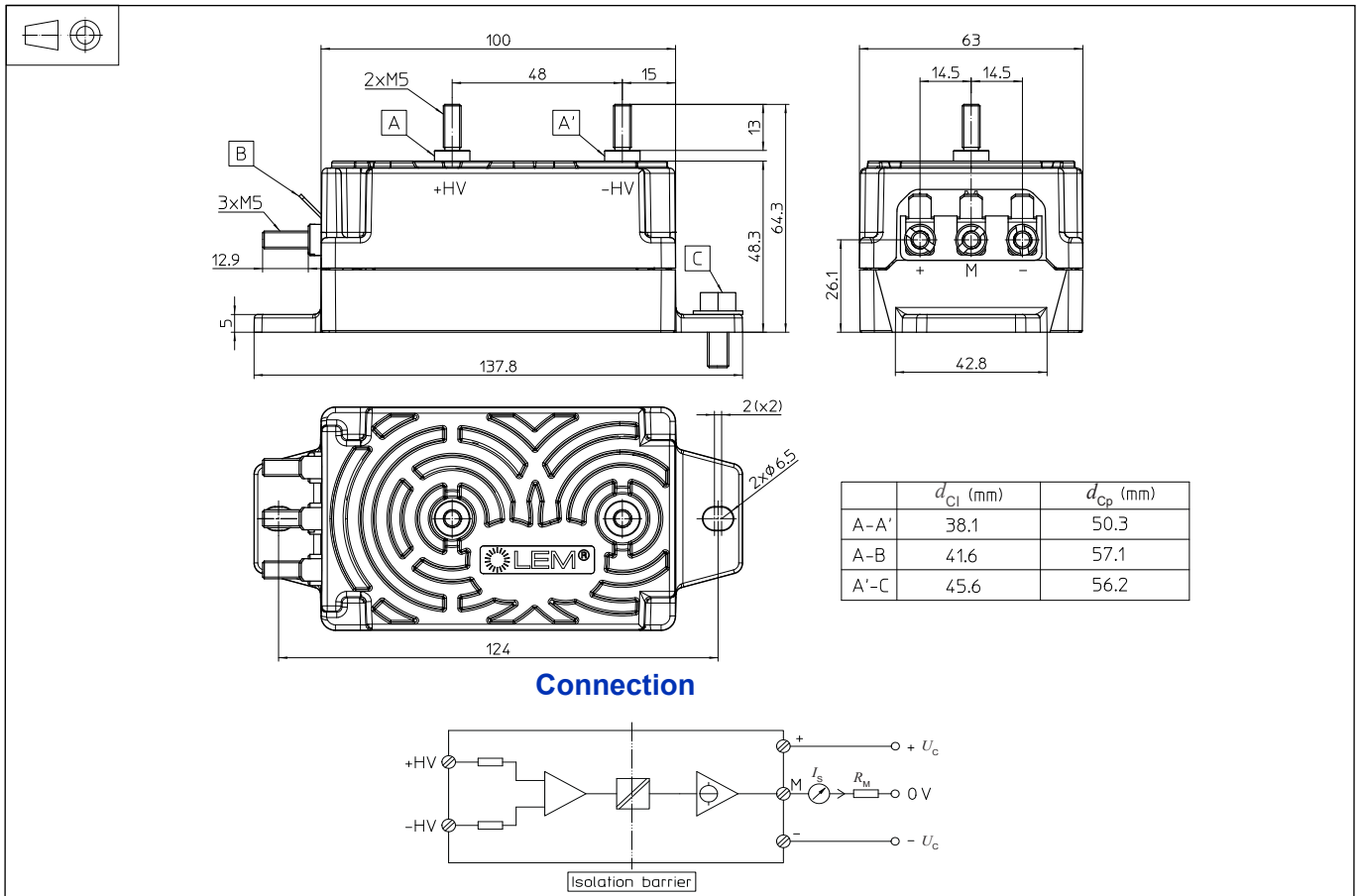


Figure 19: Delay time  $t_{D90}$  @ 90 and delay time  $t_{D10}$  @ 10





## Mechanical characteristics

- General tolerance  $\pm 0.5$  mm
- Transducer fastening
  - 2 holes  $\varnothing 6.5$  mm
  - 2 M6 steel screws
- Recommended fastening torque 4 N·m
- Connection of primary
  - 2 M5 threaded studs
  - Recommended fastening torque 2.2 N·m
- Connection of secondary
  - 3 M5 threaded studs
  - Recommended fastening torque 2.2 N·m

## Remarks

- $I_s$  is positive when a positive voltage is applied on +HV.
- The transducer is directly connected to the primary voltage.
- The primary cables have to be routed together all the way.
- The secondary cables also have to be routed together all the way.
- Installation of the transducer is to be done without primary or secondary voltage present.
- Installation of the transducer must be done unless otherwise specified on the datasheet, according to LEM Transducer Generic Mounting Rules. Please refer to LEM document N°ANE120504 available on our Web site: <https://www.lem.com/en/file/3137/download/>.

## Safety

This transducer must be used in limited-energy secondary circuits according to IEC 61010-1.



This transducer must be used in electric/electronic equipment with respect to applicable standards and safety requirements in accordance with the manufacturer's operating instructions.



Caution, risk of electrical shock

When operating the transducer, certain parts of the module can carry hazardous voltage (e.g. primary connections, power supply). Ignoring this warning can lead to injury and/or cause serious damage. This transducer is a build-in device, whose conducting parts must be inaccessible after installation. A protective housing or additional shield could be used. Main supply must be able to be disconnected.

Note: Additional information available on request.

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