

For the electronic measurement of current: DC, AC, pulsed..., with galvanic separation between the primary and the secondary circuit.



RoHS Provisional



## Features

- Hall effect measuring principle
- Multirange current transducer through PCB pattern lay-out or ASIC programming
- Galvanic separation between primary and secondary circuit
- Insulated test voltage 4300 V
- Low power consumption
- Extremely low profile 12 mm
- Single power supply +5 V
- Adjustable offset & sensitivity
- Adjustable over current detect (default:  $2.9 \times I_{PN}$  peak value)
- Adjustable response time and noise level
- $V_{ref}$  pin with adjustable REF OUT & REF IN modes
- Memory check
- Standby mode with reduced consumption
- Current range programming
- $V_{ref}$  can be switched off.

## Advantages

- Small size and space saving
- Only one design for wide primary current range
- High immunity to external interference
- 8 mm creepage /clearance
- Fast response.

## Applications

- AC variable speed and servo motor drives
- Static converters for DC motor drives
- Battery supplied applications
- Uninterruptible Power Supplies (UPS)
- Switched Mode Power Supplies (SMPS)
- Power supplies for welding applications
- Renewable Energy (Solar and Wind).

## Standards

- EN 50178: 1997
- IEC 61010-1: 2010
- IEC 61326-1: 2012
- UL 508: 2010.

## Application Domain

- Industrial.

## Absolute maximum ratings

Parameter	Symbol	Unit	Value
Supply voltage	$U_C$	V	6.5
Primary conductor temperature	$T_B$	°C	120
ESD rating, Human Body Model (HBM)	$U_{ESD}$	kV	2

Stresses above these ratings may cause permanent damage. Exposure to absolute maximum ratings for extended periods may degrade reliability.

## UL 508: Ratings and assumptions of certification

File # E189713 Volume: 2 Section: 5

### Standards

- CSA C22.2 NO. 14-10 INDUSTRIAL CONTROL EQUIPMENT - Edition 11 - Revision Date 2011/08/01
- UL 508 STANDARD FOR INDUSTRIAL CONTROL EQUIPMENT - Edition 17 - Revision Date 2010/04/15

### Ratings

Parameter	Symbol	Unit	Value
Primary involved potential		V AC/DC	600
Max surrounding air temperature	$T_A$	°C	105
Primary current	$I_P$	A	According to series primary currents
Secondary supply voltage	$U_C$	V DC	5
Output voltage	$V_{out}$	V	0 to 5

### Conditions of acceptability

When installed in the end-use equipment, consideration shall be given to the following:

- 1 - These devices have been evaluated for overvoltage category III and for use in pollution degree 2 environment.
- 2 - A suitable enclosure shall be provided in the end-use application.
- 3 - The terminals have not been evaluated for field wiring.
- 4 - These devices have been evaluated for use in 105 °C maximum surrounding air temperature.
- 5 - The secondary (Sensing) circuit is intended to be supplied by a Isolated Secondary Circuit - Limited voltage circuit defined by UL 508 paragraph 32.5. The maximum open circuit voltage potential available to the circuit and overcurrent protection shall be evaluated in the end use application.
- 6 - These devices are intended to be mounted on a printed wiring board of end-use equipment. The suitability of the connections (including spacings) shall be determined in the end-use application.
- 7 - Primary terminals shall not be straightened since assembly of housing case depends upon bending of the terminals.
- 8 - Any surface of polymeric housing have not been evaluated as insulating barrier.
- 9 - Low voltage circuits are intended to be powered by a circuit derived from an isolating source (such as a transformer, optical isolator, limiting impedance or electro-mechanical relay) and having no direct connection back to the primary circuit (other than through the grounding means).

### Marking

Only those products bearing the UL or UR Mark should be considered to be Listed or Recognized and covered under UL's Follow-Up Service. Always look for the Mark on the product.

**Insulation coordination**

Parameter	Symbol	Unit	Value	Comment
Rms voltage for AC insulation test, 50 Hz, 1 min	$U_d$	kV	4.3	
Impulse withstand voltage 1.2/50 $\mu$ s	$\dot{U}_w$	kV	8	
Partial discharge extinction rms voltage @ 10 pC	$U_e$	V	1650	
Clearance (pri. - sec.)	$d_{Cl}$	mm	8	Shortest distance through air
Creepage distance (pri. - sec.)	$d_{Cp}$	mm	8	Shortest path along device body
Case material	-	-	V0 according to UL 94	
Comparative tracking index	$CTI$	V	600	
Application example		V	600 V CAT III PD2	Reinforced insulation, non uniform field according to EN 50178
Application example		V	300 V CAT III PD2	Reinforced insulation, non uniform field according to EN 61010
Application example		V	1000 V CAT III PD2	Reinforced insulation, non uniform field according to EN 50178, EN 61010

**Environmental and mechanical characteristics**

Parameter	Symbol	Unit	Min	Typ	Max	Comment
Ambient operating temperature	$T_A$	$^{\circ}$ C	-40		105	
Ambient storage temperature	$T_S$	$^{\circ}$ C	-40		105	
Surrounding temperature according to UL 508		$^{\circ}$ C			105	
Mass	$m$	g		5		

**Electrical data  $I_{PN} = 25\text{ A}$  (default)**

 At  $T_A = 25\text{ °C}$ ,  $U_C = +5\text{ V}$ ,  $N_p = 1\text{ turn}$ ,  $R_L = 10\text{ K}\Omega$ , unless otherwise noted (see Min, Max, typ. definition paragraph in page 11).

Parameter	Symbol	Unit	Min	Typ	Max	Comment
	$I_{PN}$	At		25		Default value
Primary current, measuring range	$I_{PM}$	At	-62.5		62.5	
Number of primary turns	$N_p$			1, 2, 3		
Supply voltage	$U_C$	V	4.5	5	5.5	
Current consumption	$I_C$	mA			25	
Internal reference voltage	$V_{ref}$	V	0.48 1.48 1.63 2.48	0.5 1.5 1.65 2.5	0.52 1.52 1.67 2.52	Default
External reference voltage	$V_{ref}$	V	0.5		2.65	
Output voltage @ $I_P = 0\text{ A}$	$V_{out}$	V		$V_{ref} + V_{OE}$		
Electrical offset voltage referred to primary	$V_{OE}$	mV	-6		6	(TBC)
Temperature coefficient of $V_{ref}$ @ $I_P = 0\text{ A}$	$TCV_{ref}$	ppm/K			$\pm 190$	Internal reference (TBC)
Temperature coefficient of $V_{OE}$ @ $I_P = 0\text{ A}$	$TCV_{OE}$	mVK			$\pm 0.12$	(TBC)
Theoretical sensitivity	$G_{th}$	mV/A		32		800 mV / $I_{PN}$ , @ $U_C = 5\text{ V}$
Sensitivity error	$\epsilon_G$	%			$\pm 0.5$	Factory adjustment
Temperature coefficient of $G$	$TCG$	ppm/K			$\pm 250$	(TBC)
Linearity error 0 to $I_{PN}$	$\epsilon_L$	% of $I_{PN}$			$\pm 0.5$	@ $U_C = 5\text{ V}$
Linearity error 0 to $I_{PM}$	$\epsilon_L$	% of $I_{PM}$			$\pm 0.8$	@ $U_C = 5\text{ V}$
Magnetic offset voltage (@ $I_{PN} = 0\text{ V}$ ) after $2.5 \times I_{PN}$	$V_{OM}$	mV			$\pm 6$	
Output rms voltage noise DC .. 20 MHz referred to primary	$V_{no}$	mVpp		30 20 20		600 kHz filter 250 kHz filter (default) 100 kHz filter
Reaction time @ 10 % of $I_{PN}$ $di/dt = I_{PN}/\mu\text{s}$	$t_{ra}$	$\mu\text{s}$			1.5 2.0 2.5	600 kHz filter 250 kHz filter (default) 100 kHz filter
Step response time to 90 % of $I_{PN}$ $di/dt = I_{PN}/\mu\text{s}$	$t_r$	$\mu\text{s}$			2.0 3.5 6.0	600 kHz filter 250 kHz filter (default) 100 kHz filter
Frequency bandwidth (-3 dB)	$BW$	kHz		600 250 100		600 kHz filter 250 kHz filter (default) 100 kHz filter
Standby pin "0" level		V			0.3	
Standby pin "1" level		V	$U_C - 0.3$			
Time to switch from standby to normal mode		$\mu\text{s}$			20	
Over-current detect		V	$2.6 \times I_{PN}$	$2.9 \times I_{PN}$	$3.2 \times I_{PN}$	peak value (default)
Accuracy	$X$	% of $I_{PN}$			$\pm 1.0$	$= \epsilon_G + \epsilon_L$
Accuracy @ 85 °C	$X_{85\text{ °C}}$	% of $I_{PN}$			$\pm 3.4$	See formula <sup>1)</sup>
Accuracy @ 105 °C	$X_{105\text{ °C}}$	% of $I_{PN}$			$\pm 4.2$	See formula <sup>1)</sup>

Note: <sup>1)</sup> Accuracy @  $I_P$  and  $X_{TA} = \pm [X + (TCG/10000) \cdot (T_A - 25) + TCV_{OE} \cdot 100 \cdot (T_A - 25) / (G_{th} \cdot I_P)]$ .

**Electrical data  $I_{PN} = 15\text{ A}$** 

 At  $T_A = 25\text{ °C}$ ,  $U_C = +5\text{ V}$ ,  $N_p = 1\text{ turn}$ ,  $R_L = 10\text{ K}\Omega$ , unless otherwise noted (see Min, Max, typ. definition paragraph in page 11).

Parameter	Symbol	Unit	Min	Typ	Max	Comment
Primary nominal rms current	$I_{PN}$	At		15		Default value
Primary current, measuring range	$I_{PM}$	At	-37.5		37.5	
Number of primary turns	$N_p$			1, 2, 3		
Supply voltage	$U_C$	V	4.5	5	5.5	
Current consumption	$I_C$	mA			25	
Internal reference voltage	$V_{ref}$	V	0.48 1.48 1.63 2.48	0.5 1.5 1.65 2.5	0.52 1.52 1.67 2.52	Default
External reference voltage	$V_{ref}$	V	0.5		2.65	
Output voltage @ $I_p = 0\text{ A}$	$V_{out}$	V		$V_{ref} + V_{OE}$		
Electrical offset voltage referred to primary	$V_{OE}$	mV	-8		8	(TBC)
Temperature coefficient of $V_{ref}$ @ $I_p = 0\text{ A}$	$TCV_{ref}$	ppm/K			$\pm 190$	Internal reference (TBC)
Temperature coefficient of $V_{OE}$ @ $I_p = 0\text{ A}$	$TCV_{OE}$	mVK			$\pm 0.12$	(TBC)
Theoretical sensitivity	$G_{th}$	mV/A		53.33		800 mV / $I_{PN}$ , @ $U_C = 5\text{ V}$
Sensitivity error	$\epsilon_G$	%			$\pm 0.5$	Factory adjustment
Temperature coefficient of $G$	$TCG$	ppm/K			$\pm 250$	(TBC)
Linearity error 0 to $I_{PN}$	$\epsilon_L$	% of $I_{PN}$			$\pm 0.5$	@ $U_C = 5\text{ V}$
Linearity error 0 to $I_{PM}$	$\epsilon_L$	% of $I_{PM}$			$\pm 0.8$	@ $U_C = 5\text{ V}$
Magnetic offset voltage (@ $I_{PN} = 0\text{ V}$ ) after $2.5 \times I_{PN}$	$V_{OM}$	mV			$\pm 5$	
Output rms voltage noise DC .. 20 MHz referred to primary	$V_{no}$	mVpp		50 40 30		600 kHz filter 250 kHz filter (default) 100 kHz filter
Reaction time @ 10 % of $I_{PN}$ $dI/dt = I_{PN}/\mu\text{s}$	$t_{ra}$	$\mu\text{s}$			1.5 2.0 2.5	600 kHz filter 250 kHz filter (default) 100 kHz filter
Step response time to 90 % of $I_{PN}$ $dI/dt = I_{PN}/\mu\text{s}$	$t_r$	$\mu\text{s}$			2.0 3.5 6.0	600 kHz filter 250 kHz filter (default) 100 kHz filter
Frequency bandwidth (-3 dB)	$BW$	kHz		600 250 100		600 kHz filter 250 kHz filter (default) 100 kHz filter
Standby pin "0" level		V			0.3	
Standby pin "1" level		V	$U_C - 0.3$			
Time to switch from standby to normal mode		$\mu\text{s}$			20	
Over-current detect		V	$2.6 \times I_{PN}$	$2.9 \times I_{PN}$	$3.2 \times I_{PN}$	peak value (default)
Accuracy	$X$	% of $I_{PN}$			$\pm 1.0$	$= \epsilon_G + \epsilon_L$
Accuracy @ 85 °C	$X_{85\text{ °C}}$	% of $I_{PN}$			$\pm 3.4$	See formula <sup>1)</sup>
Accuracy @ 105 °C	$X_{105\text{ °C}}$	% of $I_{PN}$			$\pm 4.2$	See formula <sup>1)</sup>

Note: <sup>1)</sup> Accuracy @  $I_p$  and  $X_{TA} = \pm [X + (TCG/10000) \cdot (T_A - 25) + TCV_{OE} \cdot 100 \cdot (T_A - 25) / (G_{th} \cdot I_p)]$ .

**Electrical data  $I_{PN} = 8\text{ A}$** 

At  $T_A = 25\text{ °C}$ ,  $U_C = +5\text{ V}$ ,  $N_p = 1\text{ turn}$ ,  $R_L = 10\text{ K}\Omega$ , unless otherwise noted (see Min, Max, typ. definition paragraph in page 11).

Parameter	Symbol	Unit	Min	Typ	Max	Comment
Primary nominal rms current	$I_{PN}$	At		8		Default value
Primary current, measuring range	$I_{PM}$	At	-20		20	
Number of primary turns	$N_p$			1, 2, 3		
Supply voltage	$U_C$	V	4.5	5	5.5	
Current consumption	$I_C$	mA			25	
Internal reference voltage	$V_{ref}$	V	0.48 1.48 1.63 2.48	0.5 1.5 1.65 2.5	0.52 1.52 1.67 2.52	Default
External reference voltage	$V_{ref}$	V	0.5		2.65	
Output voltage @ $I_P = 0\text{ A}$	$V_{out}$	V		$V_{ref} + V_{OE}$		
Electrical offset voltage referred to primary	$V_{OE}$	mV	-15		15	(TBC)
Temperature coefficient of $V_{ref}$ @ $I_P = 0\text{ A}$	$TCV_{ref}$	ppm/K			$\pm 190$	Internal reference (TBC)
Temperature coefficient of $V_{OE}$ @ $I_P = 0\text{ A}$	$TCV_{OE}$	mVK			$\pm 0.12$	(TBC)
Theoretical sensitivity	$G_{th}$	mV/A		100		800 mV/ $I_{PN}$ @ $U_C = 5\text{ V}$
Sensitivity error	$\epsilon_G$	%			$\pm 0.5$	Factory adjustment
Temperature coefficient of $G$	$TCG$	ppm/K			$\pm 250$	(TBC)
Linearity error 0 to $I_{PN}$	$\epsilon_L$	% of $I_{PN}$			$\pm 0.5$	@ $U_C = 5\text{ V}$
Linearity error 0 to $I_{PM}$	$\epsilon_L$	% of $I_{PM}$			$\pm 0.8$	@ $U_C = 5\text{ V}$
Magnetic offset voltage (@ $I_{PN} = 0\text{ V}$ ) after $2.5 \times I_{PN}$	$V_{OM}$	mV			$\pm 4$	
Output rms voltage noise DC .. 20 MHz referred to primary	$V_{no}$	mVpp		80 60 40		600 kHz filter 250 kHz filter (default) 100 kHz filter
Reaction time @ 10 % of $I_{PN}$ $dI/dt = I_{PN}/\mu\text{s}$	$t_{ra}$	$\mu\text{s}$			1.5 2.0 2.5	600 kHz filter 250 kHz filter (default) 100 kHz filter
Step response time to 90 % of $I_{PN}$ $dI/dt = I_{PN}/\mu\text{s}$	$t_r$	$\mu\text{s}$			2.0 3.5 6.0	600 kHz filter 250 kHz filter (default) 100 kHz filter
Frequency bandwidth (-3 dB)	$BW$	kHz		600 250 100		600 kHz filter 250 kHz filter (default) 100 kHz filter
Standby pin "0" level		V			0.3	
Standby pin "1" level		V	$U_C - 0.3$			
Time to switch from standby to normal mode		$\mu\text{s}$			20	
Over-current detect		V	$2.6 \times I_{PN}$	$2.9 \times I_{PN}$	$3.2 \times I_{PN}$	peak value (default)
Accuracy	$X$	% of $I_{PN}$			$\pm 1.0$	$= \epsilon_G + \epsilon_L$
Accuracy @ 85 °C	$X_{85\text{ °C}}$	% of $I_{PN}$			$\pm 3.4$	See formula <sup>1)</sup>
Accuracy @ 105 °C	$X_{105\text{ °C}}$	% of $I_{PN}$			$\pm 4.2$	See formula <sup>1)</sup>

**Note:** <sup>1)</sup> Accuracy @  $I_P$  and  $X_{TA} = \pm [X + (TCG/10000) \cdot (T_A - 25) + TCV_{OE} \cdot 100 \cdot (T_A - 25) / (G_{th} \cdot I_P)]$ .

**Overcurrent detection (OCD) thresholds: 16 levels  $0.7 \dots 5.8 \times I_{PN\ DC}$** 

SET THRESH <sup>1)</sup>	SET <sup>1)</sup>	$I_{PN} \times$ (peak value)	OCD level [A] at $I_{PN} = 8\text{ A}$ <sup>2)</sup>	OCD level [A] at $I_{PN} = 15\text{ A}$ <sup>2)</sup>
0	000	1.7	13.6	25.5
	001	2.3	18.4	34.5
	010	2.9	23.2	43.9
	011	3.6	28.8	54.0
	100	4.0	32.0	60.0
	101	4.7	37.6	70.5
	110	5.2	41.6	78.0
	111	5.8	46.4	87.0 (<85 °C)

SET THRESH <sup>1)</sup>	SET <sup>1)</sup>	$I_{PN} \times$ (peak value)	OCD level [A] at $I_{PN} = 25\text{ A}$ <sup>2)</sup>
1	000	0.68	17.0
	001	0.93	23.3
	010	1.17	29.3
	011	1.4	35.0
	100	1.6	40.0
	101	1.9	47.5
	110	2.1	52.5
	111	2.3	57.5
0	000	1.7	42.5
	001	2.3	57.5
	010	2.9	72.5
	011	3.6	90.0 (<85 °C)
	100	4.0	100.0 (<60 °C)
	101	4.7	-
	110	5.2	-
	111	5.8	-

**Notes:** <sup>1)</sup> For detail information of the programming, please refer LEM document N° ANE131201/0 (English) and N° ANJ131201/0 (Japanese)

<sup>2)</sup> Typical response time: 2  $\mu\text{s}$ .

Typical performance characteristics  $I_{PN} = 25\text{ A}$

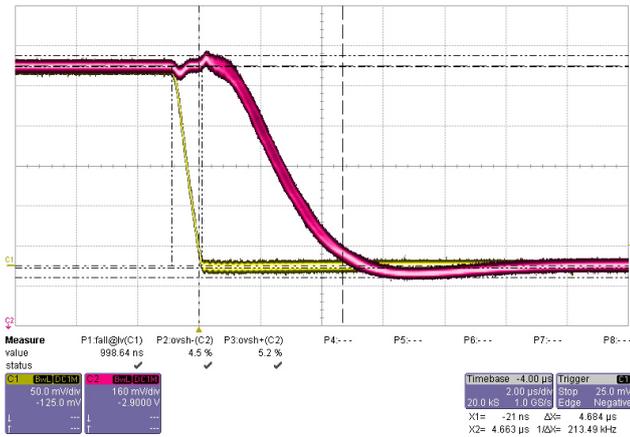


Figure 1: Step response (100 kHz filter)

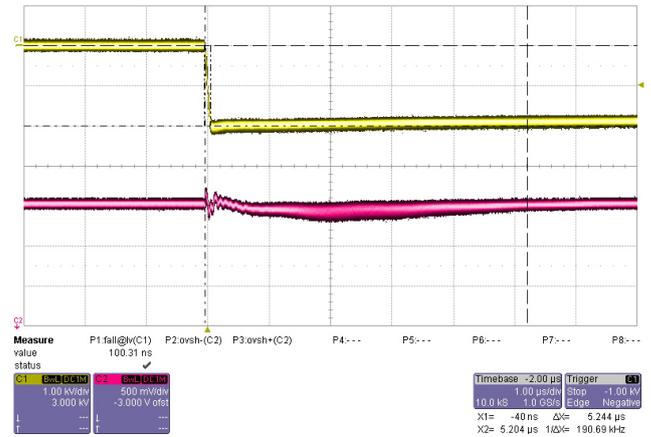


Figure 2: dv/dt (100 kHz filter)

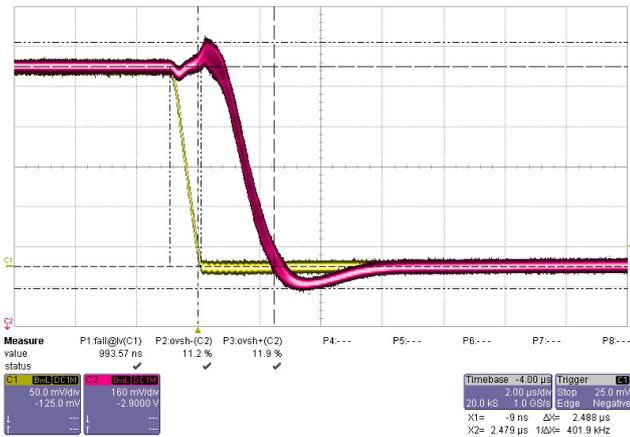


Figure 3: Step response (250 kHz filter)

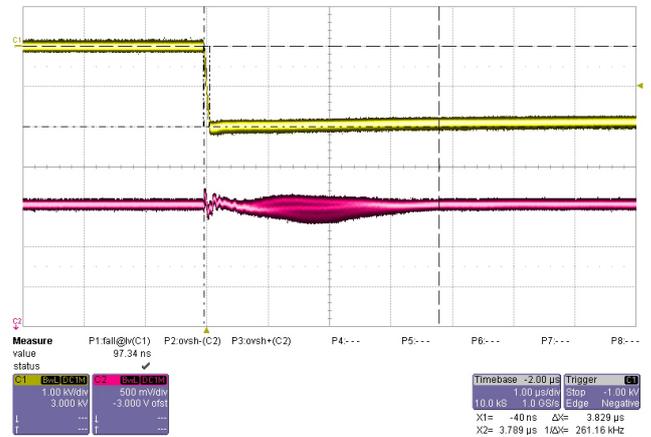


Figure 4: dv/dt (250 kHz filter)

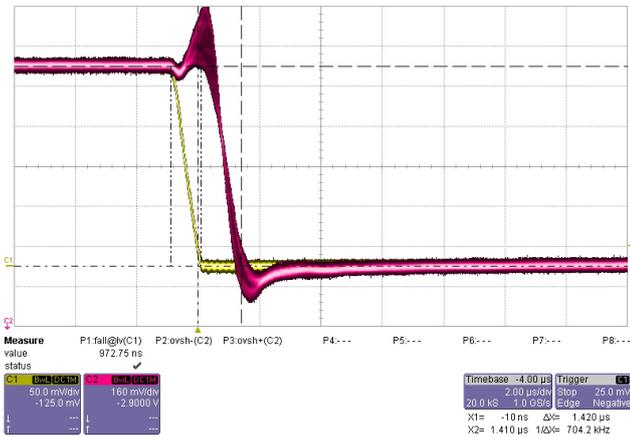


Figure 5: Step response (600 kHz filter)

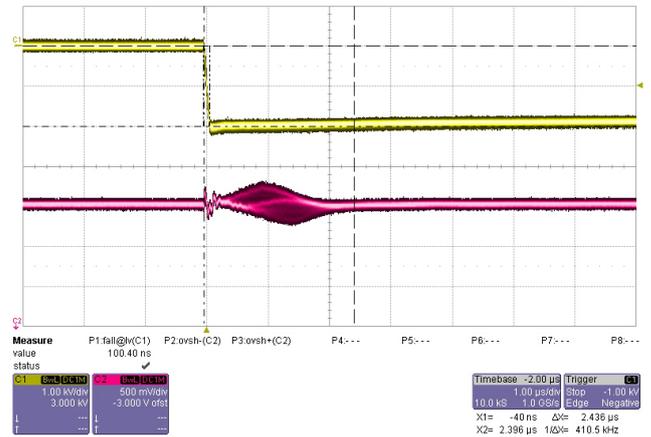


Figure 6: dv/dt (600 kHz filter)

Typical performance characteristics  $I_{PN} = 25\text{ A}$

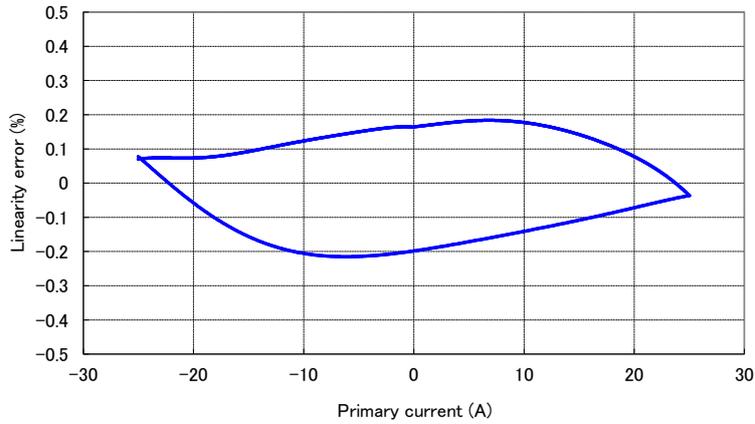


Figure 7: Linearity error ( $V_{ref} = 2.5\text{ V}$ )

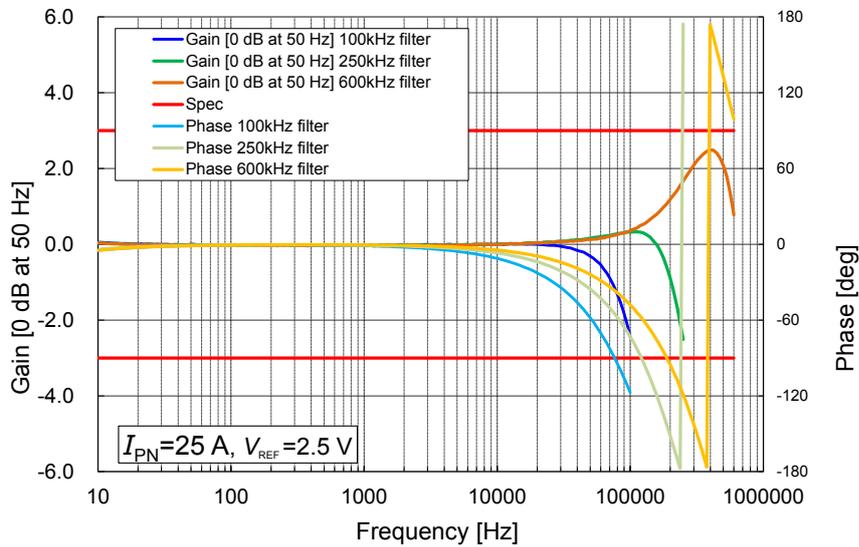


Figure 8: Frequency response

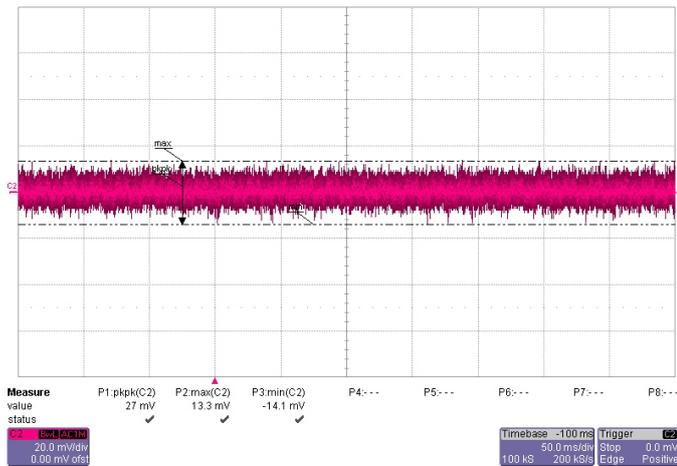


Figure 9: Output noise (250 kHz filter)

### Maximum continuous DC primary current

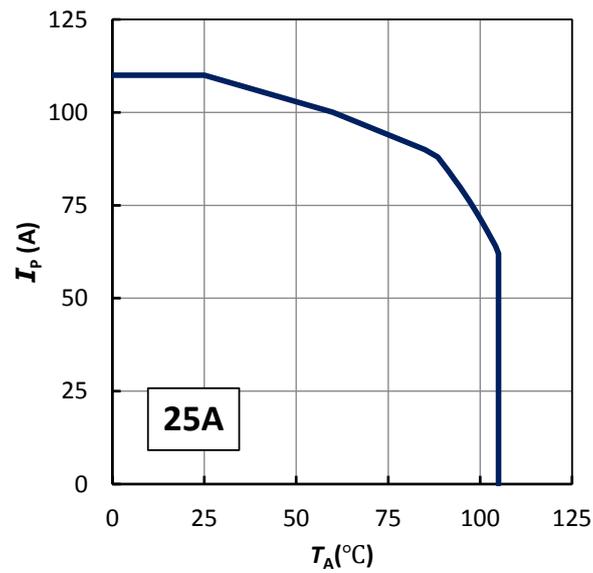
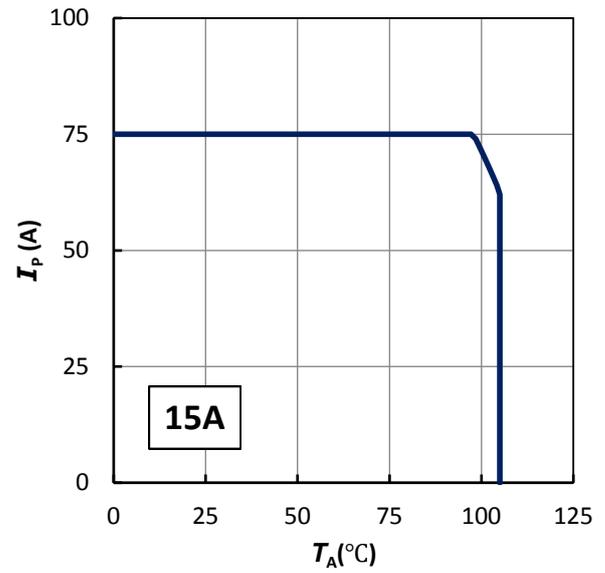
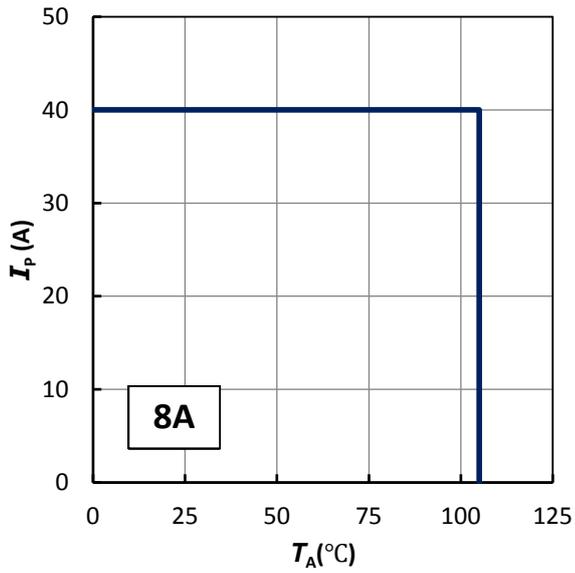


Figure 10:  $I_p$  vs  $T_A$  for HO series

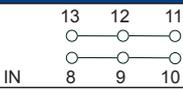
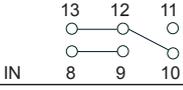
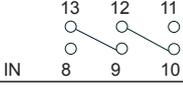
Important notice: whatever the usage and/or application, the transducer jumper temperature shall not go above the maximum rating of 120 °C as stated in page 2 of this datasheet.

## Application information

### Total primary resistance

The primary resistance is 0.36 mΩ per conductor at 25 °C.

In the following table, examples of primary resistance according to the number of primary turns.

Number of primary turns	Primary resistance current rms $R_p$ [ mΩ ]	Recommended connections	Primary nominal current $I_{PN}$ [ A ]		
			8	15	25
1	0.12		8	15	25
2	0.54		4	7.5	12.5
3	1.18		2.67	5	8.33

### Definition of typical, minimum and maximum values

Minimum and maximum values for specified limiting and safety conditions have to be understood as such as well as values shown in “typical” graphs.

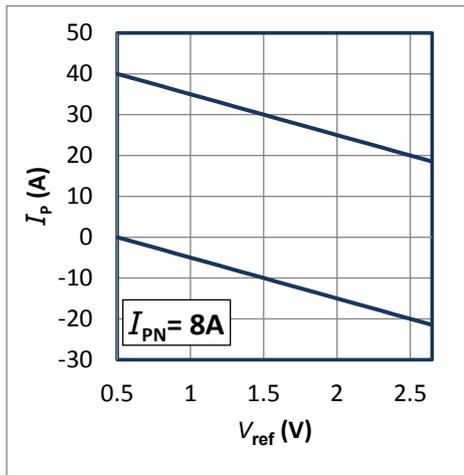
On the other hand, measured values are part of a statistical distribution that can be specified by an interval with upper and lower limits and a probability for measured values to lie within this interval.

Unless otherwise stated (e.g. “100 % tested”), the LEM definition for such intervals designated with “min” and “max” is that the probability for values of samples to lie in this interval is 99.73 %.

For a normal (Gaussian) distribution, this corresponds to an interval between -3 sigma and +3 sigma. If “typical” values are not obviously mean or average values, those values are defined to delimit intervals with a probability of 68.27 %, corresponding to an interval between -sigma and +sigma for a normal distribution.

Typical, maximal and minimal values are determined during the initial characterization of the product.

## Measuring range with external reference voltage

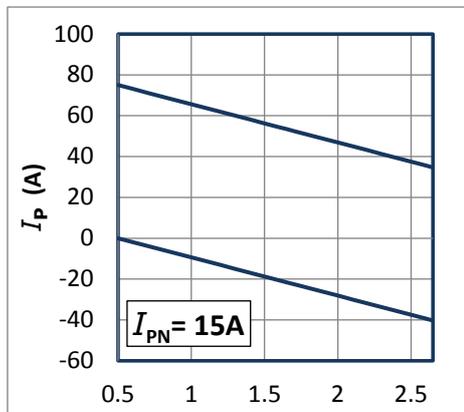


Upper limit:

$$I_p = -10 \times V_{ref} + 45 \quad (V_{ref} = 0.5 \dots 2.65 \text{ V})$$

Lower limit:

$$I_p = -10 \times V_{ref} + 5 \quad (V_{ref} = 0.5 \dots 2.65 \text{ V})$$

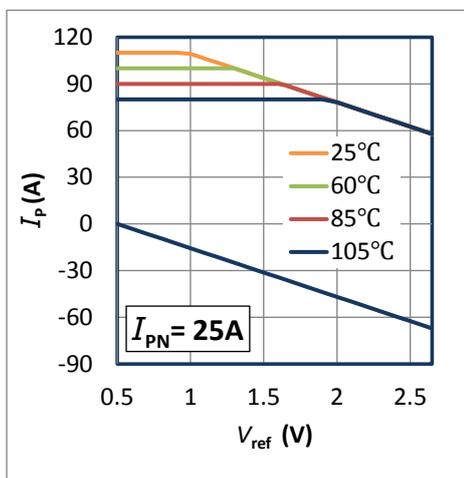


Upper limit:

$$I_p = -18.75 \times V_{ref} + 84.38 \quad (V_{ref} = 0.5 \dots 2.65 \text{ V})$$

Lower limit:

$$I_p = -18.75 \times V_{ref} + 9.38 \quad (V_{ref} = 0.5 \dots 2.65 \text{ V})$$



Upper limit:

$T_A = 105^\circ\text{C}$

$$I_p = 80 \quad (V_{ref} = 0.5 \dots 1.94 \text{ V})$$

$$I_p = 31.25 \times V_{ref} + 140.63 \quad (V_{ref} = 1.94 \dots 2.65 \text{ V})$$

$T_A = 85^\circ\text{C}$

$$I_p = 90 \quad (V_{ref} = 0.5 \dots 1.62 \text{ V})$$

$$I_p = 31.25 \times V_{ref} + 140.63 \quad (V_{ref} = 1.62 \dots 2.65 \text{ V})$$

$T_A = 60^\circ\text{C}$

$$I_p = 100 \quad (V_{ref} = 0.5 \dots 1.3 \text{ V})$$

$$I_p = 31.25 \times V_{ref} + 140.63 \quad (V_{ref} = 1.3 \dots 2.65 \text{ V})$$

$T_A = 25^\circ\text{C}$

$$I_p = 110 \quad (V_{ref} = 0.5 \dots 0.98 \text{ V})$$

$$I_p = 31.25 \times V_{ref} + 140.63 \quad (V_{ref} = 0.98 \dots 2.65 \text{ V})$$

Lower limit:

$$I_p = -31.25 \times V_{ref} + 15.63 \quad (V_{ref} = 0.5 \dots 2.5 \text{ V})$$

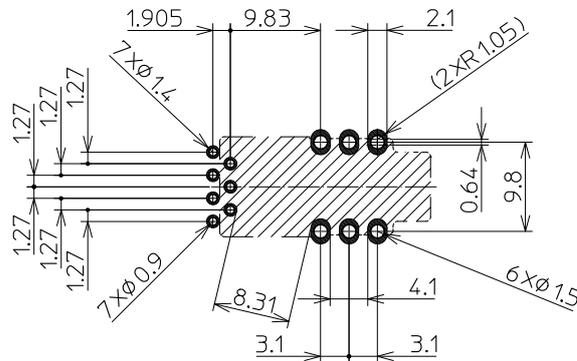
Example with  $V_{ref} = 0.5 \text{ V}$ :

- The 8 A version has a measuring range from 0 A to 40 A
- The 15 A version has a measuring range from 0 A to 75 A
- The 25 A version has a measuring range from 0 A to 80 A at  $T_A = 105^\circ\text{C}$

Example with  $V_{ref} = 1.5 \text{ V}$ :

- The 8 A version has a measuring range from -10 A to 30 A
- The 15 A version has a measuring range from -18.7 A to 56.3 A
- The 25 A version has a measuring range from -31.2 A to 90 A at  $T_A = 85^\circ\text{C}$

## PCB Footprint



### Assembly on PCB

- Recommended PCB hole diameter      1.5 mm for primary pin  
0.9 mm for secondary pin
- Maximum PCB thickness                    2.4 mm
- Wave soldering profile                    maximum 260 °C, 10 s  
No clean process only

### Safety

This transducer must be used in limited-energy secondary circuits according to IEC 61010-1.



This transducer must be used in electric/electronic equipment with respect to applicable standards and safety requirements in accordance with the manufacturer's operating instructions.



Caution, risk of electrical shock.

When operating the transducer, certain parts of the module can carry hazardous voltage (e.g. primary bus bar, power supply). Ignoring this warning can lead to injury and/or cause serious damage.

This transducer is a build-in device, whose conducting parts must be inaccessible after installation.

A protective housing or additional shield could be used.

Main supply must be able to be disconnected.

## Performance parameters definition

### Ampere-turns and amperes

The transducer is sensitive to the primary current linkage  $\Theta_p$  (also called ampere-turns).

$$\Theta_p = N_p \cdot I_p \text{ (At)}$$

Where  $N_p$  is the number of primary turn (depending on the connection of the primary jumpers)

Caution: As most applications will use the transducer with only one single primary turn ( $N_p = 1$ ), much of this datasheet is written in terms of primary current instead of current linkages. However, the ampere-turns (At) unit is used to emphasize that current linkages are intended and applicable.

### Transducer simplified model

The static model of the transducer at temperature  $T_A$  is:

$$V_{out} = G \cdot \Theta_p + \text{overall error (mV)}$$

In which overall error =

$$\varepsilon_G \cdot \Theta_p \cdot G + \varepsilon_L \cdot \Theta_p \cdot G + TCG \cdot (T_A - 25) \cdot \Theta_p \cdot G + V_{OE} + TCV_{OE} \cdot (T_A - 25) \text{ (mV)}$$

With:

- $\Theta_p = N_p \cdot I_p$  : primary current linkage (At)
- $\Theta_{Pmax}$  : max primary current linkage applied to the transducer (At)
- $V_{out}$  : output voltage (V)
- $T_A$  : ambient operating temperature ( $^{\circ}\text{C}$ )
- $V_{OE}$  : electrical offset voltage (V)
- $TCV_{OE}(T_A)$  : temperature coefficient of  $V_{OE}$  (mV/K)
- $G$  : sensitivity of the transducer (V/At)
- $TCG$  : temperature coefficient of  $G$  (%/K)
- $\varepsilon_G$  : sensitivity error (%)
- $\varepsilon_L$  : linearity error for  $\Theta_p$  (%)

This model is valid for primary ampere-turns  $\Theta_p$  between  $-\Theta_{Pmax}$  and  $+\Theta_{Pmax}$  only.

### Sensitivity and linearity

To measure sensitivity and linearity, the primary current (DC) is cycled from 0 to  $I_{P1}$ , then to  $-I_{P1}$  and back to 0 (equally spaced  $I_{P1}/10$  steps). The sensitivity  $G$  is defined as the slope of the linear regression line for a cycle between  $\pm I_{PN}$ .

The linearity error  $\varepsilon_L$  is the maximum positive or negative difference between the measured points and the linear regression line, expressed in % of  $I_{PN}$ .

### Magnetic offset

The magnetic offset voltage  $V_{OM}$  is the consequence of a current on the primary side ("memory effect" of the transducer's ferro-magnetic parts). It is measured using the following primary current cycle.  $V_{OM}$  depends on the current value  $I_{P1}$  ( $I_{P1} > I_{PM}$ ).

$$V_{OM} = \frac{V_{out}(t_1) - V_{out}(t_2)}{2}$$

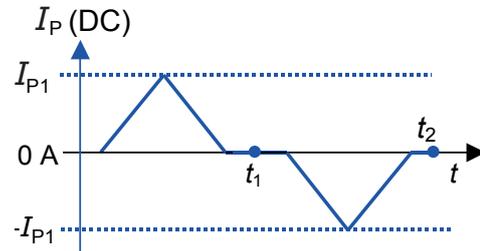


Figure 11: Current cycle used to measure magnetic and electrical offset (transducer supplied)

### Electrical offset

The electrical offset voltage  $V_{OE}$  can either be measured when the ferro-magnetic parts of the transducer are:

- completely demagnetized, which is difficult to realize,
- or in a known magnetization state, like in the current cycle shown in figure 11.

Using the current cycle shown in figure 12, the electrical offset is:

$$V_{OE} = \frac{V_{out}(t_1) + V_{out}(t_2)}{2}$$

Note: the transducer has to be demagnetized prior to the application of the current cycle (for example with a demagnetization tunnel).

### Overall accuracy

The overall accuracy at  $25^{\circ}\text{C}$   $X_G$  is the error in the  $-I_{PN} \dots +I_{PN}$  range, relative to the rated value  $I_{PN}$ . It includes:

- the electrical offset error  $V_{OE} / \Theta_p \cdot G$  (%)
- the sensitivity error  $\varepsilon_G$  (%)
- the linearity error  $\varepsilon_L$  (to  $I_{PN}$ ) (%)

### Response and reaction times

The response time  $t_r$  and the reaction time  $t_{ra}$  are shown in figure 12.

Both depend on the primary current  $di/dt$ . They are measured at nominal ampere-turns.

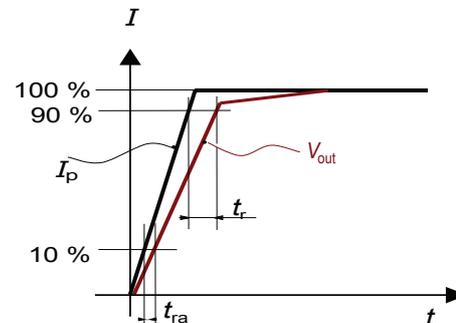


Figure 12: Response time  $t_r$  and reaction time  $t_{ra}$

