

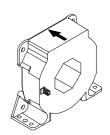
# **Current Transducer LF 1005-S**

For the electronic measurement of currents: DC, AC, pulsed..., with a galvanic isolation between the primary circuit (high power) and the secondary circuit (electronic circuit).





# $I_{PN} = 1000 A$



#### Electrical data

I <sub>PN</sub>	Primary nominal curre	ent rms		100	00		Α
I <sub>PM</sub>	Primary current, meas	uring range @ ± 24 V		0	± 150	0	Α
$\mathbf{R}_{M}$	Measuring resistance @	0	$T_A = 7$	70°C	$T_A = 8$	85°C	
			$\mathbf{R}_{Mmin}$	$R_{Mmax}$	${\bf R}_{\rm Mmin}$	$R_{Mmax}$	
	with ± 15 V	$@ \pm 1000 A_{max}$	0	18	0	15	Ω
		@ ± 1200 A max	0	7	0	4	Ω
	with ± 24 V	@ $\pm 1000 A_{max}$	5	60.5	10	57.5	Ω
		@ ± 1500 A max	5	24	10	21	Ω
I <sub>SN</sub>	Secondary nominal cu	urrent rms		200	)	ı	mΑ
$\mathbf{K}_{N}$	Conversion ratio			1:	5000		
<b>V</b> <sub>C</sub>	Supply voltage (± 5 %	b)		± 1	5 24	ļ	V
I <sub>c</sub>	Current consumption (	(± 1 mA)		28	(@ ± 24	V)+ <b>I</b> <sub>s</sub> I	mΑ

# **Accuracy - Dynamic performance data**

$\overset{\boldsymbol{x}}{\boldsymbol{e}}_{_{L}}$	Accuracy @ $\mathbf{I}_{PN}$ , $\mathbf{T}_{A}$ = 25°C Linearity error		± 0.4 < 0.1		% %
I <sub>о</sub>	Offset current @ $\mathbf{I}_P = 0$ , $\mathbf{T}_A = 25^{\circ}\mathrm{C}$ Magnetic offset current @ $\mathbf{I}_P = 0$ an	d specified $\mathbf{R}_{_{\mathrm{M}}}$ ,		Max ± 0.4	
<b>I</b> <sub>OT</sub>		erload of 3 x I <sub>PN</sub> - 10°C + 85°C - 40°C 10°C	± 0.3	± 0.2 ± 0.5 ± 0.8	mA mA mA
t <sub>,</sub> di/dt BW	Response time $^{1)}$ to 90 % of $\mathbf{I}_{PN}$ steed idd accurately followed Frequency bandwidth (- 1 dB)	р	< 1 > 100 DC 1		μs A/μs kHz

#### General data

T <sub>A</sub> T <sub>S</sub>	Ambient operating temperature Ambient storage temperature		- 40 + 85 - 45 + 100	°C
R̈́s	Secondary coil resistance @	$T_{\Delta} = 70^{\circ}C$	48	Ω
J		$T_A = 85^{\circ}C$	51	Ω
m	Mass		550	g
	Standards		EN 50178: 19	97

Note: 1) With a di/dt of 100 A/µs.

#### **Features**

- Closed loop (compensated) current transducer using the Hall effect
- Isolated plastic case recognized according to UL 94-V0.

#### **Advantages**

- Excellent accuracy
- Very good linearity
- Low temperature drift
- Optimized response time
- Wide frequency bandwidth
- No insertion losses
- High immunity to external interference
- Current overload capability.

#### **Applications**

- AC variable speed drives and servo motor drives
- Static converters for DC motor drives
- Battery supplied applications
- Uninterruptible Power Supplies (UPS)
- Switched Mode Power Supplies (SMPS)
- Power supplies for welding applications.

### **Application Domain**

• Industrial.



#### **Current Transducer LF 1005-S**

Isolation characteristics					
<b>V</b> d <b>v</b> w	Rms voltage for AC isolation test, 50 Hz, 1 mn Impulse withstand voltage 1.2/50 µs	3.8 16	kV kV		
-10	Conserve distance	Min			
dCp	Creepage distance	20.6	m m		
dCl	Clearance distance	19.6	m m		
CTI	Comparative Tracking Index (Group IIIa)	175			

## **Application examples**

According to EN 50178 and CEI 61010-1 standards and following conditions:

- Over voltage category OV 3
- Pollution degree PD2
- Non-uniform field

	EN 50178	CEI 61010-1
dCp, dCl, $\hat{\mathbf{V}}_{\mathbf{w}}$	Rated isolation voltage	Nominal voltage
Single isolation	1500 V	2000 V
Reinforced isolation	1000 V	1000 V

#### Safety



This transducer must be used in electric/electronic equipment with respect to applicable standards and safety requirements in accordance with the manufacturer's operating instructions.



Caution, risk of electrical shock

When operating the transducer, certain parts of the module can carry hazardous voltage (eg. primary busbar, power supply).

Ignoring this warning can lead to injury and/or cause serious damage.

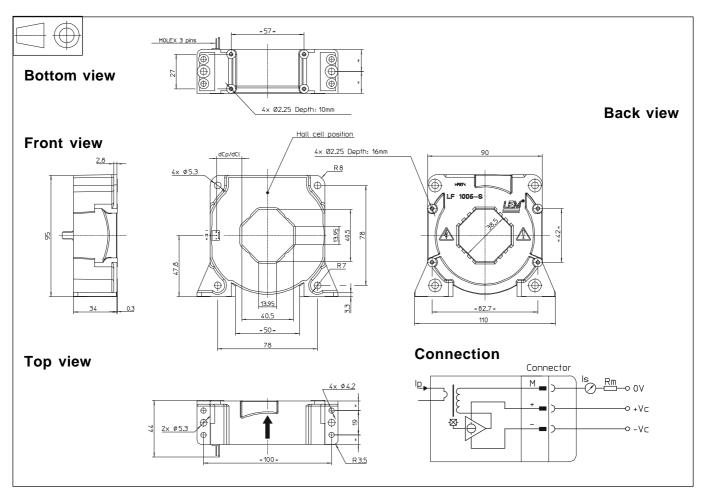
This transducer is a built-in device, whose conducting parts must be inaccessible after installation.

A protective housing or additional shield could be used.

Main supply must be able to be disconnected.



# **Dimensions** LF 1005-S (in mm. 1 mm = 0.0394 inch)



#### **Mechanical characteristics**

• General tolerance ± 0.5 mm

Transducer fastening
 Vartical position

Vertical position 2 holes Ø 5.3 mm 2 M5 steel screws

Recommended fastening torque 4 Nm or 2.96 Lb. - Ft. or 4 holes  $\varnothing$  4.2 mm

4 holes Ø 4.2 mm 4 M4 steel screws

Recommended fastening torque 3.2 Nm or 2.37 Lb. - Ft.

r 4 holes Ø 2.25 mm depth10 mm 4 x PT KA30 screws long 10 mm

Recommended fastening torque 0.9 Nm or 0.66 Lb. - Ft.

• Transducer fastening

Horizontal position 4 holes Ø 5.3 mm 4 M5 steel screws

Recommended fastening torque 4 Nm or 2.96 Lb. - Ft.

r 4 holes Ø 2.25 mm depth16 mm

4 x PT KA30 screws long 16 mm

Fastening torque, maxi 1 Nm or 0.74 Lb. - Ft.
• Primary through-hole 40.5 x 13 mm

or ∅ 38 mm • Connection of secondary Molex 6410

3 Tin plated pins.

#### Remarks

- $I_s$  is positive when  $I_p$  flows in the direction of the arrow.
- Temperature of the primary conductor should not exceed 100°C.
- Dynamic performances (di/dt and response time) are best with a single bar completely filling the primary hole.
- This is a standard model. For different versions (supply voltages, turns ratios, unidirectional measurements...), please contact us.

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