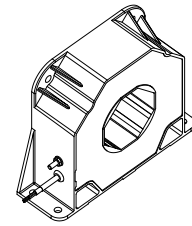


# Current Transducer LF 2005-S/SP9

For the electronic measurement of currents: DC, AC, pulsed..., with galvanic separation between the primary circuit and the secondary circuit.

$$I_{PN} = 1000 \text{ A}$$



RoHS  
16178

## Electrical data

$I_{PN}$	Primary nominal RMS current	1000	A				
$I_{PM}$	Primary current, measuring range @ $\pm 24 \text{ V}$	0 ... $\pm 2000$	A				
$\hat{I}_{Pmax}$	Primary withstand peak current (maximum)	50	kA				
$R_M$	Measuring resistance	$T_A = 70 \text{ }^\circ\text{C}$		$T_A = 85 \text{ }^\circ\text{C}$			
		$R_{Mmin}$	$R_{Mmax}$	$R_{Mmin}$	$R_{Mmax}$	$\Omega$	
		with $\pm 15 \text{ V}$	@ $\pm 1000 \text{ A}_{max}$	0	27	0	26
			@ $\pm 1700 \text{ A}_{max}$	0	2	0	1
		with $\pm 24 \text{ V}$	@ $\pm 1000 \text{ A}_{max}$	0	69	3	68
	@ $\pm 2000 \text{ A}_{max}$	0	18	3	17		
$I_{SN}$	Secondary nominal RMS current	200	mA				
$N_P/N_S$	Turns ratio	1 : 5000					
$U_C$	Supply voltage ( $\pm 10 \%$ )	$\pm 15 \dots 24$	V				
$I_C$	Current consumption	33 (@ $\pm 24 \text{ V}$ ) + $I_S$	mA				

## Accuracy - Dynamic performance data

$\epsilon_L$	Linearity error	< 0.1	%
$t_{D90}$	Delay time to 90 % of the final output value for $I_{PN}$ step <sup>1)</sup>	< 1	$\mu\text{s}$
$BW$	Frequency bandwidth (-1 dB)	DC ... 100	kHz

## Test circuit

$N_T$	Number of turns (test winding)	1000	
$R_T$	Resistance of test winding @ $T_A = 85$	16	$\Omega$
$I_T$	Test current	0.1 <sup>2)</sup>	A

### Remarks:

- Use a current generator for the test winding (high impedance)
- Otherwise a minimum resistance in series with the test winding is needed:
  - $30 \text{ } \Omega$  @  $T_A = -25 \dots +85 \text{ }^\circ\text{C}$
  - $50 \text{ } \Omega$  @  $T_A = -40 \dots +85 \text{ }^\circ\text{C}$

## General data

$T_A$	Ambient operating temperature	-40 ... +85	$^\circ\text{C}$
$T_{Ast}$	Ambient storage temperature	-40 ... +85	$^\circ\text{C}$
$R_S$	Resistance of secondary winding @ $T_A = 70 \text{ }^\circ\text{C}$	33	$\Omega$
		@ $T_A = 85 \text{ }^\circ\text{C}$	34
$m$	Mass	1.4	kg
	Standards	EN 50155: 2021 <sup>3)</sup> EN 50121-3-2: 2016	

Notes: <sup>1)</sup> For a  $di/dt = 100 \text{ A}/\mu\text{s}$

<sup>2)</sup> Maximum 1 A during 10 seconds 6 times per hour

<sup>3)</sup> Additional information available on request.

## Features

- Closed loop (compensated) current transducer using the Hall effect
- Insulating plastic case recognized according to UL 94-V0.

## Special features

- $I_{PN} = 1000 \text{ A}$
- $I_{PM} = 0 \dots \pm 2000 \text{ A}$
- $U_C = \pm 15 \dots 24 (\pm 10 \%) \text{ V}$
- $U_d = 12 \text{ kV}$
- $N_T = 1000$  turns
- $T_A = -40 \text{ }^\circ\text{C} \dots 85 \text{ }^\circ\text{C}$
- Secondary connection on shielded cable  $5 \times 0.5 \text{ mm}^2$ .

## Advantages

- Excellent accuracy
- Very good linearity
- Low temperature drift
- Optimized response time
- Wide frequency bandwidth
- No insertion losses
- High immunity to external interference
- Current overload capability.

## Applications

- Single or three phase inverter
- Propulsion and braking chopper
- Propulsion converter
- Auxiliary converter
- Battery charger.

## Application Domain

- Railway (fixed installations and onboard).

## Current Transducer LF 2005-S/SP9

### Insulation coordination

$U_d$	RMS voltage for AC insulation test, 50 Hz, 1 min	12 <sup>1)</sup> 500 <sup>2)</sup>	kV V
$U_t$	Partial discharge RMS test voltage ( $q_m < 10$ pC)	$\geq 4.1$ <sup>3)</sup> Min	kV
$d_{cp}$	Creepage distance	51.5	mm
$d_{cl}$	Clearance	51.5	mm
CTI	Comparative tracking index (group I)	600	

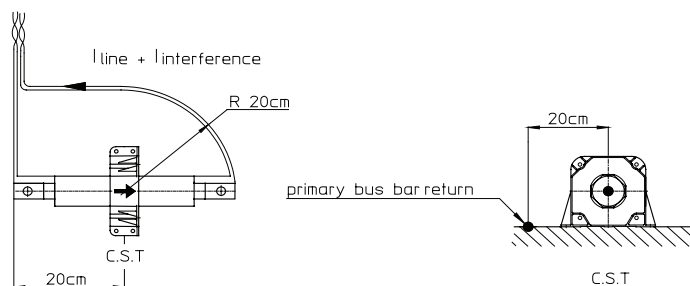
**Notes:** 1) Between primary and secondary + test  
 2) Between shield and secondary + test  
 3) Test performed with a non-insulated bus bar (dimension 290 × 50 × 10 mm) centered in the aperture.

### DC offset [At]

Temperature range	Maximum range of measured current			
	-100 ... +100 A	-500 ... +500 A	-1000 ... +1000 A	-2000 ... +2000 A
-25 °C ... +85 °C	±3.6	±3.8	±4.0	±4.8
-40 °C ... +85 °C	±5.1	±5.3	±5.5	±6.3

Maximum DC offset for different ranges of temperature and measured current.

### Wiring plan for DC component measuring



### Accuracy for the measurement of a single frequency signal

Frequency	20 ... 200 Hz		200 ... 3000 Hz	
	Amplitude Error [%]	Phase Error [%]	Amplitude Error [%]	Phase Error [%]
0.1 ... 0.5 A	±55	-15.0	±55	22
0.5 ... 1 A	±17	-14.0	±48	22
1 ... 2 A	±7.0	-7.4	±32	14
2 ... 10 A	±6.6	-1.6	±17	6.2
10 ... 20 A	±3.7	< -1.0	±6.8	-1.4
20 ... 50 A	±2.8	< -1.0	±3.6	< -1.0

Amplitude error: in % of the measured signal.  
 Phase error: in degrees with respect to the measured signal.  
 Maximum amplitude and phase errors for single frequency signals.  
 High error values are due to zero-crossing distortion.

### Accuracy for the measurement of a signals added to a DC current $\geq 10$ A

Frequency	20 ... 200 Hz		200 ... 3000 Hz	
	Amplitude Error [%]	Phase Error [%]	Amplitude Error [%]	Phase Error [%]
0.1 ... 0.5 A	$\pm 2.2$	-1.6	$\pm 4.4$	1.4
0.5 ... 1 A	$\pm 2.5$	-1.6	$\pm 4.1$	< -1.0
1 ... 2 A	$\pm 2.5$	-1.6	$\pm 4.1$	< -1.0
2 ... 10 A	$\pm 6.1$	-1.1	$\pm 7.0$	< -1.0
10 ... 20 A	$\pm 6.1$	< -1.0	$\pm 8.8$	< -1.0
20 ... 50 A	$\pm 6.0$	< -1.0	$\pm 7.5$	< -1.0

Amplitude error: in % of the measured signal.

Phase error: in degrees with respect to the measured signal.

Maximum amplitude and phase errors for signals added to a DC fundamental.

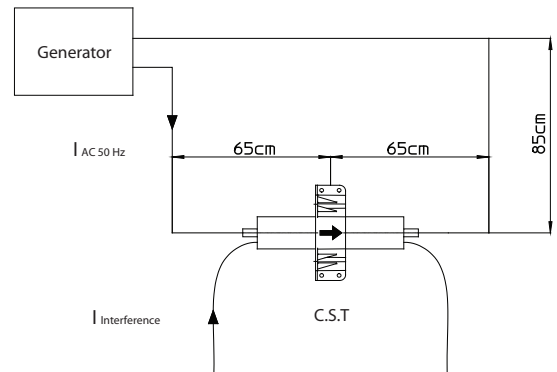
### Accuracy for the measurement of a signals added to an AC (fundamental) current ( $15 \text{ Hz} < f < 100 \text{ Hz}$ ), $\geq 10$ A RMS

Frequency	20 ... 200 Hz		200 ... 3000 Hz	
	Amplitude Error [%]	Phase Error [%]	Amplitude Error [%]	Phase Error [%]
0.1 ... 0.5 A	$\pm 1.6$	< -1.0	$\pm 2.3$	< -1.0
0.5 ... 1 A	$\pm 1.2$	< -1.0	$\pm 1.9$	< -1.0
1 ... 2 A	$\pm 0.9$	< -1.0	$\pm 1.3$	< -1.0
2 ... 10 A	$\pm 0.6$	< -1.0	$\pm 0.8$	< -1.0
10 ... 20 A	$\pm 0.6$	< -1.0	$\pm 0.7$	< -1.0
20 ... 50 A	$\pm 1.0$	< -1.0	$\pm 1.0$	< -1.0

Amplitude error: in % of the measured signal.

Phase error: in degrees with respect to the measured signal.

Maximum amplitude and phase errors for signals added to an AC fundamental.

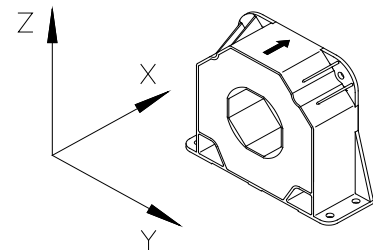


Wiring plan for measurements with an AC component.

### Influence regarding external magnetic fields

Frequency	0 ... 5 Hz	0 ... 5 Hz
Direction	Max error [mAt <sub>RMS</sub> per A/m]	Max error [mAt <sub>RMS</sub> per A/m]
X-axis	0.16	0.18
Y-axis	3.3	5.3
Z-axis	0.04	0.08

Error in the measurement of the primary current [mA<sub>RMS</sub>] due to external magnetic fields at the specified frequencies for the three axes of the transducer



Orientation of transducer during magnetic field sensitivity testing.

