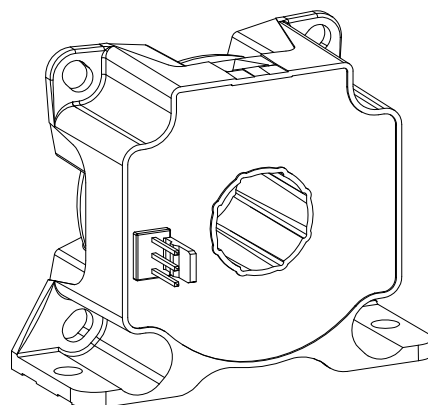


For the electronic measurement of current: DC, AC, pulsed..., with galvanic separation between the primary and the secondary circuit.



Features

- Bipolar and insulated current measurement
- Current output
- Closed loop (compensated) current transducer
- Panel mounting.

Special features

- $I_{PN} = 100 \text{ A}$
- $I_{PM} = 0 \dots \pm 200 \text{ A}$
- $N_s = 1000$ turns.

Advantages

- High accuracy
- Very low offset drift over temperature.

Applications

- Windmill inverters
- Test and measurement
- AC variable speed and servo motor drives
- Static converters for DC motors drives
- Battery supplied applications
- Uninterruptible Power Supplies (UPS)
- Switched Mode Power Supplies (SMPS)
- Power supplies for welding applications.

Standards

- IEC 61010-1: 2010
- IEC 61800-5-1: 2007
- IEC 62109-1: 2010
- UL 508: 2013.

Application Domain

- Industrial.

Absolute maximum ratings

Parameter	Symbol	Unit	Value
Maximum supply voltage (working) (−40 °C ... 85 °C)	$\pm U_{C \max}$	V	±15.75
Maximum primary conductor temperature	$T_{B \max}$	°C	100
Maximum steady state primary current (−40 °C ... 85 °C)	$I_{P N \max}$	A	100

Stresses above these ratings may cause permanent damage.
Exposure to absolute maximum ratings for extended periods may degrade reliability.

UL 508: Ratings and assumptions of certification

File # E189713 Volume: 2 Section: 9

Standards

- USR indicates investigation to the Standard for Industrial Control Equipment UL 508.
- CNR indicates investigation to the Canadian standard for Industrial Control Equipment CSA C22.2 No. 14-13.

Ratings

Parameter	Unit	Value
Primary involved potential	V AC/DC	1500
Maximum surrounding air temperature	°C	85
Primary current	A	0 ... 100
Secondary supply voltage	V DC	0 ... ±15.75
Secondary current	mA	0 ... 100

Conditions of acceptability

When installed in the end-use equipment, with primary feedthrough potential involved of 1500 V AC/DC, consideration shall be given to the following:

- 1 - *These products must be mounted in a suitable end-use enclosure.*
- 2 - *The secondary pin terminals have not been evaluated for field wiring.*
- 3 - *Low voltage control circuit shall be supplied by an isolating source (such as transformer, optical isolator, limiting impedance or electro-mechanical relay).*
- 4 - *Based on the temperature test performed on LF 210-S series, the primary bar or conductor shall not exceed 100 °C in the end use application.*
- 5 - *LF 210-S series shall be used in a pollution degree 2.*

Marking

Only those products bearing the UL or UR Mark should be considered to be Listed or Recognized and covered under UL's Follow-Up Service. Always look for the Mark on the product.

Insulation coordination

Parameter	Symbol	Unit	Value	Comment
RMS voltage for AC insulation test, 50 Hz, 1 min	U_d	kV	3.5	Type test
Impulse withstand voltage 1.2/50 μ s	U_{Ni}	kV	8.8	According to IEC 61800-5-1
Partial discharge RMS test voltage ($q_m < 10$ pC)	U_t	kV	1.65	Test carried out with a non insulated bar and completely filling the primary hole. According to IEC 61800-5-1
Clearance (pri. - sec.)	d_{Cl}	mm	10.2	Shortest distance through air
Creepage distance (pri. - sec.)	d_{cp}	mm	11	Shortest path along device body
Application example Rated insulation RMS voltage	U_{Nm}	V	1000	Basic insulation according to IEC 61800-5-1, CAT III, PD2 (table value)
Application example Rated insulation RMS voltage	U_{Nm}	V	300	Reinforced insulation according to IEC 61800-5-1, CAT III, PD2 (table value)
Case material	-	-	V0	According to UL 94
Comparative tracking index	CTI		600	

Environmental and mechanical characteristics

Parameter	Symbol	Unit	Min	Typ	Max	Comment
Ambient operating temperature	T_A	°C	-40		85	
Ambient storage temperature	T_S	°C	-50		90	
Mass	m	g		75		

Electrical data

At $T_A = 25\text{ °C}$, $\pm U_C = \pm 15\text{ V}$, $R_M = 1\text{ }\Omega$, unless otherwise noted.

Lines with a * in the conditions column apply over the $-40 \dots 85\text{ °C}$ ambient temperature range.

Parameter	Symbol	Unit	Min	Typ	Max	Conditions
Primary nominal RMS current	I_{PN}	A			100	*
Primary current, measuring range	I_{PM}	A	-200		200	* With $\pm U_C = \pm 15\text{ V}$ For other conditions, see Figure 1
Measuring resistance	R_M	Ω	0 ¹⁾			* Max value of R_M is given in Figure 1
Secondary nominal RMS current	I_{SN}	A	-0.1		0.1	*
Resistance of secondary winding	R_S	Ω			8.5	$R_S(T_A) = R_S \times (1 + 0.004 \times (T_A + \Delta\text{temp} - 25))$ Estimated temperature increase @ I_{PN} is $\Delta\text{temp} = 15\text{ °C}$
Secondary current	I_S	A	-0.2		0.2	*
Number of secondary turns	N_S			1000		
Nominal sensitivity	S_N	mA/A		1		
Supply voltage	$\pm U_C$	V	± 11.4		± 15.75	*
Current consumption	I_C	mA		$33 + I_S$ $35 + I_S$		$\pm U_C = \pm 12\text{ V}$ $\pm U_C = \pm 15\text{ V}$
Offset current, referred to primary	I_O	A	-0.15		0.15	
Temperature variation of I_O , referred to primary	I_{OT}	A	-0.2		0.2	*
Magnetic offset current (@ $3 \times I_{PN}$), referred to primary	I_{OM}	A		± 0.2		
Sensitivity error	ε_S	%	-0.15		0.15	*
Linearity error	ε_L	% of I_{PN}	-0.05		0.05	*
Total error at I_{PN}	ε_{tot}	% of I_{PN}	-0.2 -0.2		0.2 0.2	* $25 \dots 85\text{ °C}$ * $-40 \dots 85\text{ °C}$
RMS noise current referred to primary	I_{no}	mA		20		1 Hz to 100 kHz (see Figure 4)
Delay time @ 10 % of I_{PN}	t_{D10}	μs		< 0.5		0 to 200 A, 75 A/ μs , $R_M = 10\text{ }\Omega$
Delay time @ 90 % of I_{PN}	t_{D90}	μs		< 0.5		0 to 200 A, 75 A/ μs , $R_M = 10\text{ }\Omega$ (see Figure 2)
Frequency bandwidth	BW	kHz		100		$R_M = 50\text{ }\Omega$; -3 dB

Note: ¹⁾ Other values of minimum values according to conditions of use are given in [Figure 1](#).

Definition of typical, minimum and maximum values

Minimum and maximum values for specified limiting and safety conditions have to be understood as such as well as values shown in "typical" graphs. On the other hand, measured values are part of a statistical distribution that can be specified by an interval with upper and lower limits and a probability for measured values to lie within this interval. Unless otherwise stated (e.g. "100 % tested"), the LEM definition for such intervals designated with "min" and "max" is that the probability for values of samples to lie in this interval is 99.73 %. For a normal (Gaussian) distribution, this corresponds to an interval between -3 sigma and +3 sigma. If "typical" values are not obviously mean or average values, those values are defined to delimit intervals with a probability of 68.27 %, corresponding to an interval between -sigma and +sigma for a normal distribution.

Typical, minimum and maximum values are determined during the initial characterization of the product.

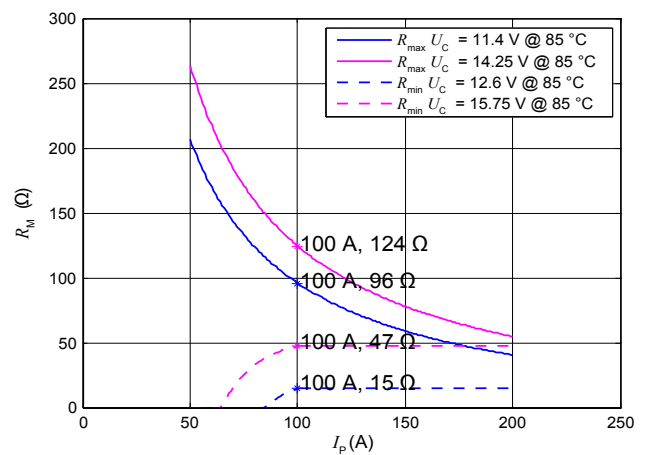
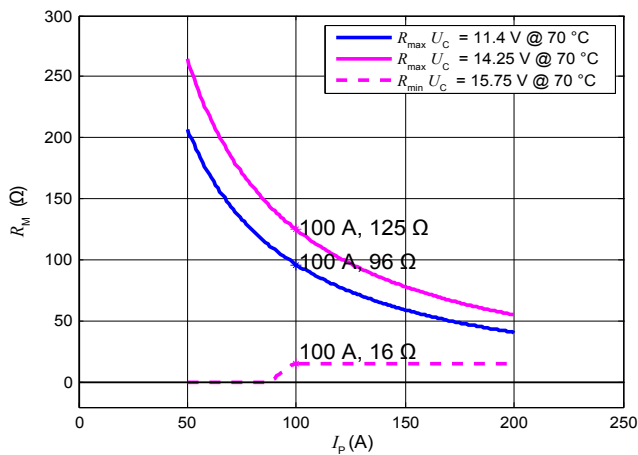


Figure 1: Maximum measuring resistance

$$R_{M \max} = N_S \times \frac{U_{C \min} - 0.3 \text{ V}}{I_P} - R_{S \max} - 4.1 \Omega$$

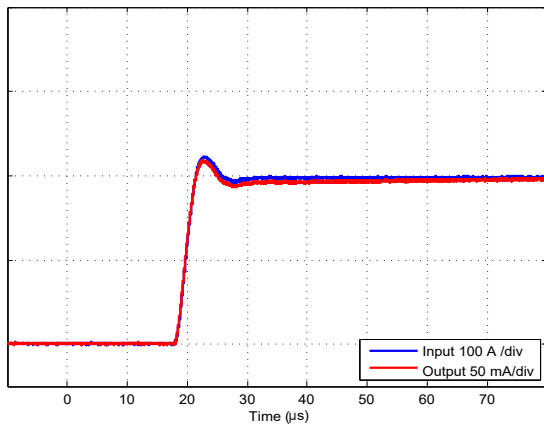


Figure 2: Typical delay time (0 to 200 A, 75 A/μs, with $R_M = 10 \Omega$)

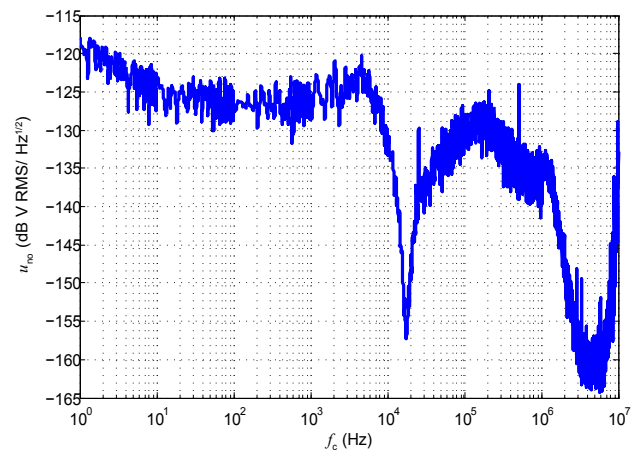


Figure 3: RMS noise voltage referred to primary u_{no} with $R_M = 10 \Omega$

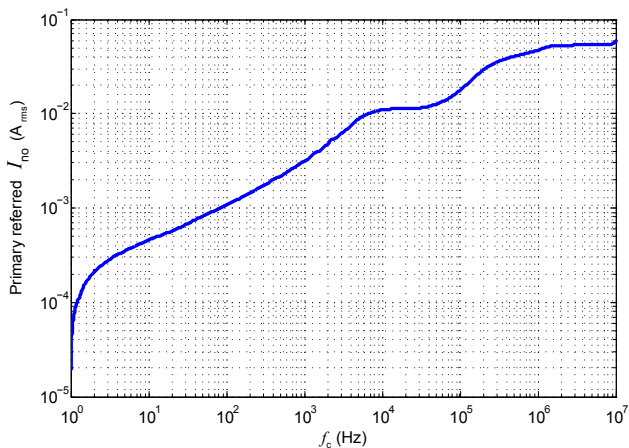


Figure 4: RMS noise current referred to primary with $R_M = 10 \Omega$

To calculate the noise in a frequency band f_1 to f_2 , the formula is:

$$I_{no}(f_1 \dots f_2) = \sqrt{I_{no}(f_2)^2 - I_{no}(f_1)^2}$$

with $I_{no}(f)$ read from figure 4 (typical, RMS value).

Example:

What is the noise from 10^3 to 10^6 Hz?

Figure 4 gives $I_{no}(10^3 \text{ Hz}) = 3 \text{ mA}$

and $I_{no}(10^6 \text{ Hz}) = 50 \text{ mA}$.

The output RMS noise current is therefore:

$$\sqrt{(50 \times 10^{-3})^2 - (3 \times 10^{-3})^2} = 50 \text{ mA referred to primary}$$

Typical performance characteristics continued

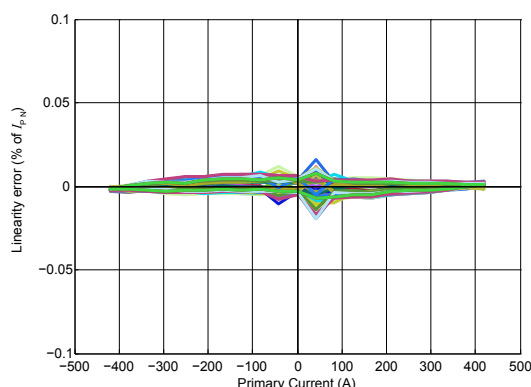


Figure 5: Linearity

Performance parameters definition

Sensitivity and linearity

To measure sensitivity and linearity, the primary current (DC) is cycled from 0 to I_{PM} , then to $-I_{PM}$ and back to 0 (equally spaced $I_{PM}/10$ steps).

The sensitivity S is defined as the slope of the linear regression line for a cycle between $\pm I_{PM}$.

The linearity error ε_L is the maximum positive or negative difference between the measured points and the linear regression line, expressed in % of the maximum measured value.

Magnetic offset

The magnetic offset I_{OM} is the change of offset after a given current has been applied to the input. It is included in the linearity error as long as the transducer remains in its measuring range.

Electrical offset

The electrical offset current I_{OE} is the residual output current when the input current is zero.

Total error

The total error ε_{tot} is the error at $\pm I_{PN}$, relative to the rated value I_{PN} .

It includes all errors mentioned above.

Delay times

The delay time t_{D10} @ 10 % and the delay time t_{D90} @ 90 % with respect to the primary are shown in the next figure.

Both slightly depend on the primary current di/dt .

They are measured at nominal current.

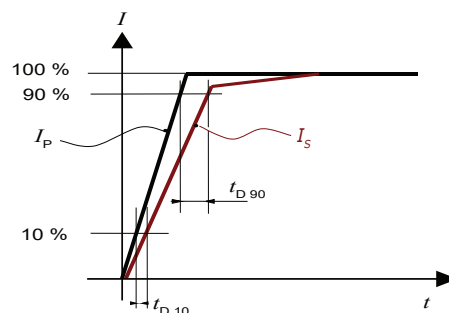


Figure 6: t_{D10} (delay time @ 10 %) and t_{D90} (delay time @ 90 %)

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