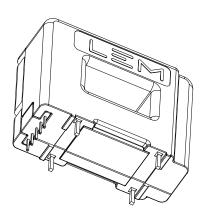


Current Transducer LZSR 150-P/SP1

 $I_{\rm P\,N}$ = 150 A

For the electronic measurement of current: DC, AC, pulsed..., with galvanic separation between the primary and the secondary circuit.





Features

- Closed loop multi-range current transducer
- Voltage output
- Unipolar supply voltage.

Special feature

• Higher measuring range.

Advantages

- Very low offset drift
- Very good du/dt immunity.

Applications

- AC variable speed and servo motor drives
- Battery supplied applications
- Uninterruptible Power Supplies (UPS)
- Switched Mode Power Supplies (SMPS)
- Power supplies for welding applications
- Solar inverters.

Standards

- IEC 61800-3: 2017
- IEC 61800-5-1: 2007
- IEC 62109-1: 2010
- IEC 62477-1: 2012
- UL 508: 2018.

Application Domain

Industrial.





Safety



If the device is used in a way that is not specified by the manufacturer, the protection provided by the device may be compromised. Always inspect the electronics unit and connecting cable before using this product and do not use it if damaged. Mounting assembly shall guarantee the maximum primary busbar temperature, fulfill clearance and creepage distance, minimize electric and magnetic coupling, and unless otherwise specified can be mounted in any orientation



Caution, risk of electrical shock

This transducer must be used in limited-energy secondary circuits SELV according to IEC 61800-5-1, in electric/electronic equipment with respect to applicable standards and safety requirements in accordance with the manufacturer's operating specifications.

When operating the transducer, certain parts of the module can carry hazardous voltage (e.g. primary busbar, power supply). All installations, maintenance, servicing operations and use must be carried out by trained and qualified personnel practicing applicable safety precautions.

If the transducer is used in a manner not specified by the manufacturer, the protection provided by the equipment may be impaired.

Ignoring this warning can lead to injury and/or cause serious damage.

This transducer is a build-in device, whose hazardous live parts must be inaccessible after installation.

This transducer must be mounted in a suitable end-enclosure.

Use caution during installation and use of this product; high voltages and currents may be present in circuit under test.

This transducer is a built-in device, not intended to be cleaned with any product. Nevertheless if the user must implement cleaning or washing process, validation of the cleaning program has to be done by himself.



ESD susceptibility

The product is susceptible to be damaged from an ESD event and the personnel should be grounded when handling it.

Do not dispose of this product as unsorted municipal waste. Contact a qualified recycler for disposal.

Although LEM applies utmost care to facilitate compliance of end products with applicable regulations during LEM product design, use of this part may need additional measures on the application side for compliance with regulations regarding EMC and protection against electric shock. Therefore LEM cannot be held liable for any potential hazards, damages, injuries or loss of life resulting from the use of this product.



Underwriters Laboratory Inc. recognized component





Absolute maximum ratings

Parameter	Symbol	Unit	Value
Maximum supply voltage	$U_{\mathrm{C\ max}}$	V	7
Maximum primary conductor temperature	$T_{ m B\ max}$	°C	110
Maximum primary current	I_{Pmax}	Α	10 × I _{PN}
Electrostatic discharge voltage (HBM - Human Body Model)	$U_{\rm ESD\; HBM}$	kV	4

Stresses above these ratings may cause permanent damage.

Exposure to absolute maximum ratings for extended periods may degrade reliability.

UL 508: Ratings and assumptions of certification

File # E189713 Volume: 2 Section: 14

Standards

- CSA C22.2 NO. 14-10 INDUSTRIAL CONTROL EQUIPMENT Edition 11
- UL 508 STANDARD FOR INDUSTRIAL CONTROL EQUIPMENT Edition 17

Ratings

Parameter	Symbol	Unit	Value
Primary potential involved		V AC/DC	1000
Max surrounding air temperature	T_{A}	°C	85
Primary current	I_{P}	А	Primary nominal current
Transducer supply	U_{c}	V DC	5
Output signal	U_{out}	V	0 to 5

Conditions of acceptability

When installed in the end-use equipment, consideration shall be given to the following:

- 1 These devices must be mounted in a suitable end-use enclosure.
- 2 The terminals have not been evaluated for field wiring.
- 3 The LZSR Series shall be used in a pollution degree 2 environment or better.
- 4 Low voltage circuits are intended to be powered by a circuit derived from an isolating source (such as a transformer, optical isolator, limiting impedance or electro-mechanical relay) and having no direct connection back to the primary circuit (other than through the grounding means).
- 5 These devices are intended to be mounted on the printed wiring board of the end-use equipment (with a minimum CTI of 100).
- 6 LZSR Series: based on results of temperature tests, in the end-use application, a maximum of 110°C cannot be exceeded on the primary conductor.

Marking

Only those products bearing the UL or UR Mark should be considered to be Listed or Recognized and covered under UL's Follow-Up Service. Always look for the Mark on the product.





Insulation coordination

Parameter	Symbol	Unit	Value	Comment
RMS voltage for AC insulation test, 50 Hz, 1 min	U_{d}	kV	3	
Impulse withstand voltage 1.2/50 μs	U_{Ni}	kV	8	
Insulation resistance	R_{INS}	GΩ	> 200	measured at 500 V DC
Partial discharge RMS test voltage ($q_{\rm m}$ < 10 pC)	U_{t}	kV	1650	
Comparative tracking index	CTI		600	
Case material	-	-	V0	According to UL 94
Clearance (pri sec.)	d_{CI}	mm	12.9	Shortest distance through air
Creepage distance (pri sec.)	d_{Cp}	mm	12.9	Shortest path along device body
Application example System voltage RMS		V	600	Reinforced insulation according to IEC 61800-5-1, IEC 62109-1 CAT III, PD2
Application example System voltage RMS		V	1000	Basic insulation according to IEC 61800-5-1, IEC 62109-1 CAT III, PD2

Environmental and mechanical characteristics

Parameter	Symbol	Unit	Min	Тур	Max	Comment
Ambient operating temperature	T_{A}	°C	-40		85	
Ambient storage temperature	T_{Ast}	°C	-55		125	
Mass	m	g		44		



LZSR 150-P/SP1

Electrical data

At $T_{\rm A}$ = 25 °C, $U_{\rm C}$ = +5 V, $N_{\rm P}$ = 1 turn, $R_{\rm L}$ = 10 k Ω internal reference unless otherwise noted (see Min, Max, typ. definition paragraph in page 6). Lines with a * in the comment column apply over the -40 ... 85 °C ambient temperature range.

Parameter	Symbol	Unit	Min	Тур	Max		Comment
Primary nominal RMS current	I_{PN}	А		150		*	
Primary current, measuring range	I_{PM}	Α	-450		450	*	
Supply voltage	U_{c}	V	4.75	5	5.25	*	
Current consumption	$I_{\mathtt{C}}$	mA		$18 + \frac{I_{\rm P}({\rm mA})}{N_{\rm S}}$	$20 + \frac{I_{\rm p}({\rm mA})}{N_{\rm S}}$		N _s = 1277 turns
Reference voltage @ I_p = 0 A	U_{ref}	V	2.485	2.5	2.515		Internal reference
Output voltage	U_{out}	V	0.25		4.75		with $U_{\rm c}$ = +5 V
Output voltage @ I_P = 0 A	U_{out}	V		U_{ref}			
Electrical offset voltage	U_{OE}	mV	-2.5		2.5		100 % tested $U_{\rm out}$ – $U_{\rm ref}$
Electrical offset current referred to primary	I_{OE}	mA	-600		600		100 % tested
Temperature coefficient of $I_{\text{O E}}$ referred to primary	TCI _{OE}	A/K	-0.002		0.002	*	
Temperature coefficient of $U_{\mathrm{ref}}^{-1)}$	$TCU_{\rm ref}$	ppm/K			±100	*	Internal reference
Temperature coefficient of $U_{\rm out}$ @ $I_{\rm P}$ = 0 A	TCU_{out}	ppm/K			±3	*	ppm/K of 2.5 V
Nominal sensitivity	S_{N}	mV/A		4.166			625 mV/I _{PN}
Sensitivity error	$\varepsilon_{_{S}}$	% of $I_{\scriptscriptstyle{PN}}$	-0.8		0.8		100 % tested
Temperature coefficient of S	TCS	ppm/K			75	*	
Linearity error	ε_{L}	% of $I_{_{\mathrm{P}\mathrm{N}}}$	-0.10		0.10		
Magnetic offset current (10 × I_{PN}) referred to primary	$I_{ m OM}$	mA	-156		156		
Noise voltage spectral density 100 Hz 100 kHz	u_{no}	μV/Hz½		0.92			
Peak-to-peak noise voltage DC 10 kHz DC 100 kHz DC 1 MHz	U_{nopp}	mVpp		0.2 0.33 1			
Primary current, detection threshold	$I_{ m PTh}$	Α	2.59 × I _{PN}	2.65 × I _{PN}	2.72 × I _{PN}		
Delay time of threshold output for high value	t _{D H Th}	μs		1.4	2.2	*	Overcurrent detection measured over temperature
Delay time to 10 % of the final output value for $I_{\rm PN}$ step	t _{D 10}	μs			1		d <i>i</i> /d <i>t</i> = 50 A∕µs
Delay time to 80 % of the final output value for $I_{\rm PN}$ step	t _{D 80}	μs			3		di/dt = 50 A/µs primary busbar with the full size of hole dimensions: 11 × 20.5 [H × W in mm]
Delay time to 80 % of the final output value for $I_{\rm PN}$ step	t _{D 80}	μs			2.2		di/dt = 50 A/µs primary busbar with client-specific dimensions: 2 × 15 [H × W in mm]
Frequency bandwidth (±3 dB)	BW	kHz	200				
Total error	\mathcal{E}_{tot}	% of $I_{\rm PN}$			1		See formula note 2)
Total error @ $T_{\rm A}$ = 85 °C	€ _{tot 85}	% of $I_{\rm PN}$			1.4		See formula note 2)
Sum of sensitivity and linearity error	$\varepsilon_{_{\mathrm{SL}}}$	% of $I_{\rm PN}$			0.83		See formula note 3)
Sum of sensitivity and linearity error @ $T_{\rm A}$ = 85 °C	€ _{S L 85}	% of $I_{\scriptscriptstyle{PN}}$			1.2		See formula note 3)

1) ppm refer to full-scale which corresponds to a primary nominal RMS current 2) $\frac{TCS}{I_{DR}} + \frac{TCI_{OE}}{I_{DN}} \times 10^6$ 3) $\varepsilon_{\text{tot}}(T_{\text{A}}) = \varepsilon_{\text{tot}} \times 25 + \frac{TCI_{OE}}{10^4} \times |T_{\text{A}}|^2 \times 25|$ $\varepsilon_{\text{SL}}(T_{\text{A}}) = \varepsilon_{\text{tot}} \times 10^6 \times 10^6$ Notes:

$$\varepsilon_{\text{tot}}(T_{\text{A}}) = \varepsilon_{\text{tot 25}} + \frac{TCS + \frac{TCI_{\text{OE}}}{I_{\text{PN}}} \times 10^6}{4 \cdot \text{A}} \times |T_{\text{A}} - 25|$$

 $TCS + \frac{TCI_{OE}}{I} \times 10^6$ $\frac{I_{PN}}{10^4}$ x $|T_A-25|$ $\varepsilon_{\text{SL}}(T_{\text{A}}) = \varepsilon_{\text{SL 25}} + \dots$



LZSR 150-P/SP1

Definition of typical, minimum and maximum values

Minimum and maximum values for specified limiting and safety conditions have to be understood as such as well as values shown in "typical" graphs.

On the other hand, measured values are part of a statistical distribution that can be specified by an interval with upper and lower limits and a probability for measured values to lie within this interval.

Unless otherwise stated (e.g. "100 % tested"), the LEM definition for such intervals designated with "min" and "max" is that the probability for values of samples to lie in this interval is 99.73 %.

For a normal (Gaussian) distribution, this corresponds to an interval between -3 sigma and +3 sigma. If "typical" values are not obviously mean or average values, those values are defined to delimit intervals with a probability of 68.27 %, corresponding to an interval between -sigma and +sigma for a normal distribution.

Typical, maximal and minimal values are determined during the initial characterization of the product.



Typical performance characteristics

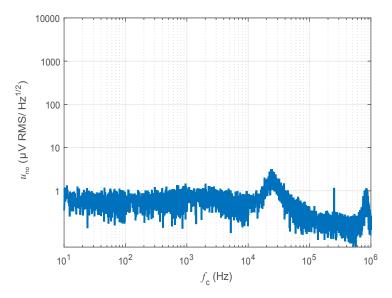


Figure 1: Noise voltage spectral density referred to primary

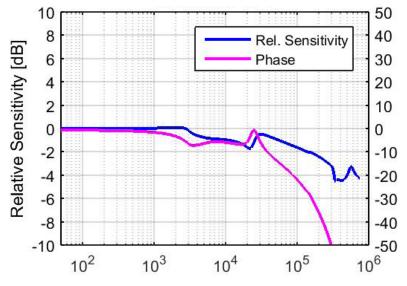


Figure 2: Frequency response





Terms and definitions

Ampere-turns and amperes

The transducer is sensitive to the primary current linkage $\Theta_{\rm p}$ (also called ampere-turns).

$$\Theta_{\rm P} = N_{\rm P} \cdot I_{\rm P}$$

Where $N_{\rm p}$ is the number of primary turn (depending on the connection of the primary jumpers).

Caution: As most applications will use the transducer with only one single primary turn ($N_{\rm p}$ = 1), much of this datasheet is written in terms of primary current instead of current linkages. However, the ampere-turns (A) unit is used to emphasis that current linkages are intended and applicable.

Simplified transducer model

The static model of the transducer with voltage output at temperature $T_{\rm a}$ is:

$$U_{\text{out}} = S \cdot \Theta_{\text{P}} \cdot (1 + \varepsilon)$$

In which (referred to primary):

$$\varepsilon \cdot \Theta_{\mathrm{P}} = I_{\mathrm{O}\,\mathrm{E}} + I_{\mathrm{O}\,\mathrm{T}} + \varepsilon_{\mathrm{S}} \cdot \Theta_{\mathrm{P}} + \varepsilon_{\mathrm{S}\,\mathrm{T}} \cdot \Theta_{\mathrm{P}} + \varepsilon_{\mathrm{L}}(\Theta_{\mathrm{P}\,\mathrm{max}}) \cdot \Theta_{\mathrm{P}\,\mathrm{max}} + I_{\mathrm{O}\,\mathrm{M}}$$

 $\Theta_{P} = N_{P} \cdot I_{P}$: primary current linkage (A)

 $\Theta_{P,max}$: maximum primary current linkage applied to

the transducer
: secondary current (A)

 $I_{
m S}$: secondary current (A) $U_{
m cut}$: output voltage (V)

S: sensitivity of the transducer

 T_{A} : ambient operating temperature (°C)

 $\begin{array}{ll} I_{\text{OE}} & \text{: electrical offset current (A)} \\ I_{\text{OM}} & \text{: magnetic offset current (A)} \\ I_{\text{O} \ T} & \text{: temperature variation of } I_{\text{OE}} \text{ (A)} \\ \varepsilon_{c} & \text{: sensitivity error at 25 °C} \end{array}$

 S_S : sensitivity error at 25 $S_{S,T}$: thermal drift of S : linearity error for $\Theta_{P,max}$

This model is valid for primary ampere-turns $\Theta_{\rm p}$ between $-\Theta_{\rm P\,max}$ and $+\Theta_{\rm P\,max}$ only.

This is the absolute maximum error. As all errors are independent, a more realistic way to calculate the error would be to use the following formula:

$$\varepsilon = \sqrt{\sum_{i=1}^{N} \varepsilon_i^2}$$

Sensitivity and linearity

To measure sensitivity and linearity, the primary current (DC) is cycled from 0 to $I_{\rm p}$, then to $-I_{\rm p}$ and back to 0 (equally spaced $I_{\rm p}/10$ steps). The sensitivity S is defined as the slope of the linear regression line for a cycle between $\pm I_{\rm p\,N}$.

The linearity error $\varepsilon_{\rm L}$ is the maximum positive or negative difference between the measured points and the linear regression line, expressed in % of $I_{\rm PN}$.

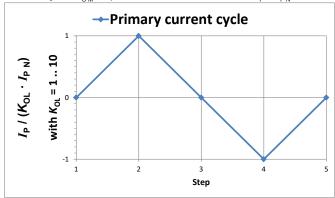




Performance parameters definition

Magnetic offset referred to primary

The magnetic offset current $I_{\rm OM}$ is the consequence of a current on the primary side ("memory effect" of the transducer's ferromagnetic parts). It is measured using the following primary current cycle. $I_{\rm OM}$ depends on the current value $I_{\rm P} \geq I_{\rm PN}$.



 $K_{\text{\tiny OL}}$: Overload factor

Figure 3: Current cycle used to measure magnetic and electrical offset (transducer supplied)

$$I_{\rm OM} = \frac{I_{\rm P\,(3)} - I_{\rm P\,(5)}}{2}$$

Electrical offset referred to primary

Using the current cycle shown in figure 3, the electrical offset current I_{OE} is the residual output referred to primary when the input current is zero.

$$I_{\text{O E}} = \frac{I_{\text{P(3)}} + I_{\text{P(5)}}}{2}$$

The temperature variation $I_{\rm O\, au}$ of the electrical offset current $I_{\rm O\, au}$ is the variation of the electrical offset from 25 °C to the considered temperature.

$$I_{\text{O }T}(T) = I_{\text{O E}}(T) - I_{\text{O E}}(25 \text{ }^{\circ}\text{C})$$

Delay times

The delay time $t_{\rm D\,10}$ @ 10 % and the delay time $t_{\rm D\,80}$ @ 80 % with respect to the primary are shown in the next figure. Both slightly depend on the primary current ${\rm d}i/{\rm d}t$. They are measured at nominal current.

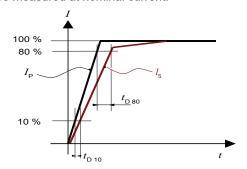


Figure 4: $t_{\rm D\,10}$ (delay time @ 10 %) and $t_{\rm D\,80}$ (delay time @ 80 %)

Total error referred to primary

The total error $\varepsilon_{\rm tot}$ is the error at $\pm I_{\rm P\,N},$ relative to the rated value $I_{\rm P\,N}.$

It includes all errors mentioned above

- the electrical offset I_{OF}
- the magnetic offset I_{OM}
- the sensitivity error ε_s
- the linearity error ε_{L} (to I_{PN}).

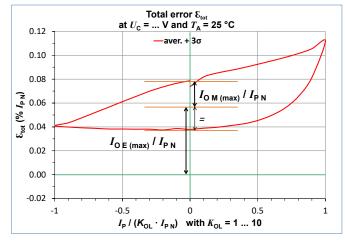


Figure 5: Total error ε_{tot}



Application information

Filtering and decoupling

Supply voltage U_c

The transducer has internal decoupling capacitors, but in the case of a power supply with high impedance, it is highly recommended to provide local decoupling (100 nF or more, located close to the transducer) as it may reduce disturbance on transducer output U_{out} and reference U_{ref} due to high varying primary current. The transducer power supply rejection ratio is low at high frequency.

Output U_{out}

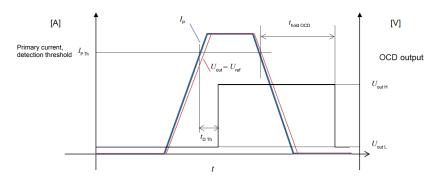
The output $U_{\rm out}$ has a very low output impedance of typically 1 Ohm; it can drive capacitive loads of up to 100 nF directly. Adding series resistance Rf of several tenths of Ohms allows much larger capacitive loads Cf (higher than 1 μ F). Empirical evaluation may be necessary to obtain optimum results. The minimum load resistance on $U_{\rm out}$ is 1 kOhm.

Reference U_{ref}

Likewise output U_{out} , the U_{ref} has a very low output impedance of typically 1 Ohm; it can drive capacitive loads of up to 100 nF directly. Adding series resistance Rf of several tenths of Ohms allows much larger capacitive loads Cf (higher than 1 μ F). Empirical evaluation may be necessary to obtain optimum results. The minimum load resistance on U_{ref} is 10 kOhms.

Overcurrent detection definition

The overcurrent detection function generates an output signal to the OCD pin whenever the primary current exceeds a pre-programmed threshold value. Once the overcurrent event is detected, the CMOS-type OCD signal changes from low logic (< 30 % $U_{\rm c}$) to high logic value (> 70 % $U_{\rm c}$). In order to avoid undesirable glitches, the OCD signal is digitally filtered and the OCD signal output is held for 1 ms in high logic value after the last overcurrent event detection.



Parameter	Symbol	Unit	Min	Тур	Max	Comment
High-level output voltage	U_{outH}	V	3.5			With $U_{\rm c}$ = +5 V and source current of 3 mA
Low-level output voltage	$U_{\rm outL}$	V			1.5	With $U_{\rm c}$ = +5 V and sink current of 3 mA





External reference voltage

The REF pin can be used either as a reference voltage output or as a reference voltage input.

When used in reference voltage output, the internal reference voltage $U_{\rm ref}$ is used by the transducer as the reference point for bipolar measurements.

The internal reference voltage output accuracy is defined in the electrical parameter data.

When used in reference voltage input, an external reference voltage is connected to the REF pin.

In this case, the maximum allowable reference voltage range is 0.5 V - 2.75 V.

The REF pin must be able to source or sink an input current of 1.5 mA maximum.

If the reference voltage is not used, the REF pin should be left unconnected.

The following graph shows the $I_{\rm p}$ current versus forced extreme external $U_{\rm ref}$:

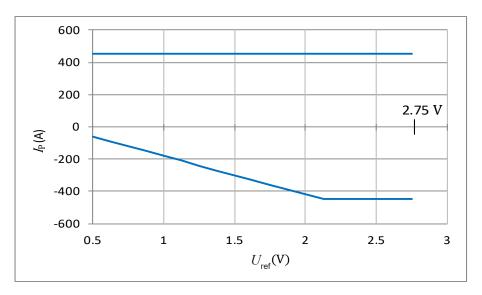


Figure 6: Measuring range versus external $U_{\mbox{\tiny ref}}$

Upper limit: $I_P = 450 (U_{ref} = 0.5 \text{ V} ... 2.75 \text{ V})$

 $I_{\rm p}$ = -240 * $U_{\rm ref}$ + 60 ($U_{\rm ref}$ = 0.5 V ... 2.12 V) $I_{\rm p}$ = -450 ($U_{\rm ref}$ = 2.12 V ... 2.75 V) Lower limit:

Example with $U_{ref} = 1.65 \text{ V}$:

The transducer has a measuring range from -336 A to +450 A.

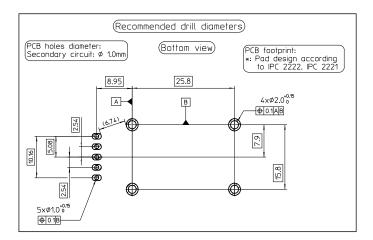
Example with $U_{ref} = 0.5 \text{ V}$:

The transducer has a measuring range from -60 A to +450 A.





PCB footprint



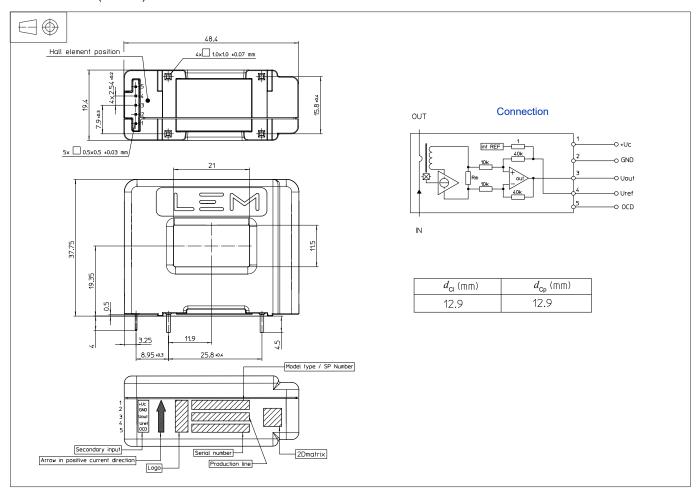
Assembly on PCB

- Recommended PCB hole diameter
- Maximum PCB thickness
- Wave soldering profile
 No clean process only
- 1 mm for secondary pin 2 mm for retention pin 2.9 mm maximum 260 °C for 10 s





Dimensions (in mm)



Mechanical characteristics

General tolerance

±0.6 mm

Remarks

- It is advised to use a primary conductor (busbar) that fills transducer through-hole.
- Be aware of the influence of the external field if nearby transducers are too close (relay, capacitor, choke...).
- Installation of the transducer must be done, unless otherwise specified on the datasheet, according to LEM Transducer Generic Mounting Rules. Please refer to LEM document N°ANE120504 available on our web site: https://www.lem.com/en/file/3137/download.





Packaging information

Standard delivery in cardboard: L \times W \times H: 300 \times 200 \times 200 mm

Each cardboard contains 60 parts, placed into 4 Polystyrene-made trays of 15 parts each one. Both trays and cardboard are ESD-compliant.

The typical weight of the cardboard is 3 Kg.

