

AUTOMOTIVE CURRENT TRANSDUCER OPEN LOOP TECHNOLOGY

SMU01



Introduction

The SMU family is a transducer for DC measurement in high power and low voltage automotive applications. It offers a galvanic separation between the primary circuit (high power) and the secondary circuit (electronic circuit).

The SMU family gives you a choice of having different current measuring ranges in the same housing (from ± 400 A up to ± 1500 A).

Features

- Open Loop transducer using the Hall effect sensor
- High insulation level
- Unipolar +5 V DC power supply
- Primary current measuring range up to ± 1500 A
- Maximum RMS primary admissible current: defined by the busbar, the magnetic core or ASIC $T < +125$ °C
- Operating temperature range: -40 °C $< T < +125$ °C
- Output voltage: fully ratio-metric (in sensitivity and offset).

Advantages

- Excellent accuracy
- Very good linearity
- Very low thermal offset drift
- Very low thermal sensitivity drift
- High frequency bandwidth
- No insertion losses.

Automotive applications

- Battery management
- EV, Hybrid and utility vehicles.

Principle of SMU family

The open loop transducers uses a Hall effect integrated circuit. The magnetic flux density B , contributing to the rise of the Hall voltage, is generated by the primary current I_p to be measured.

The current to be measured I_p is supplied by a current source i.e. battery or generator (Figure 1).

Within the linear region of the hysteresis cycle, B is proportional to:

$$B(I_p) = a \times I_p$$

The Hall voltage is thus expressed by:

$$U_{Hall} = (c_{Hall} / d) \times I_{Hall} \times a \times I_p$$

Except for I_p , all terms of this equation are constant. Therefore:

$$U_{Hall} = b \times I_p$$

a constant

b constant

c_{Hall} Hall coefficient

d thickness of the Hall plate

I_{Hall} current across the Hall plates

The measurement signal U_{Hall} amplified to supply the user output voltage or current.

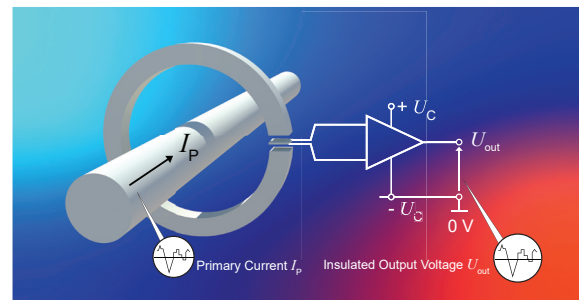
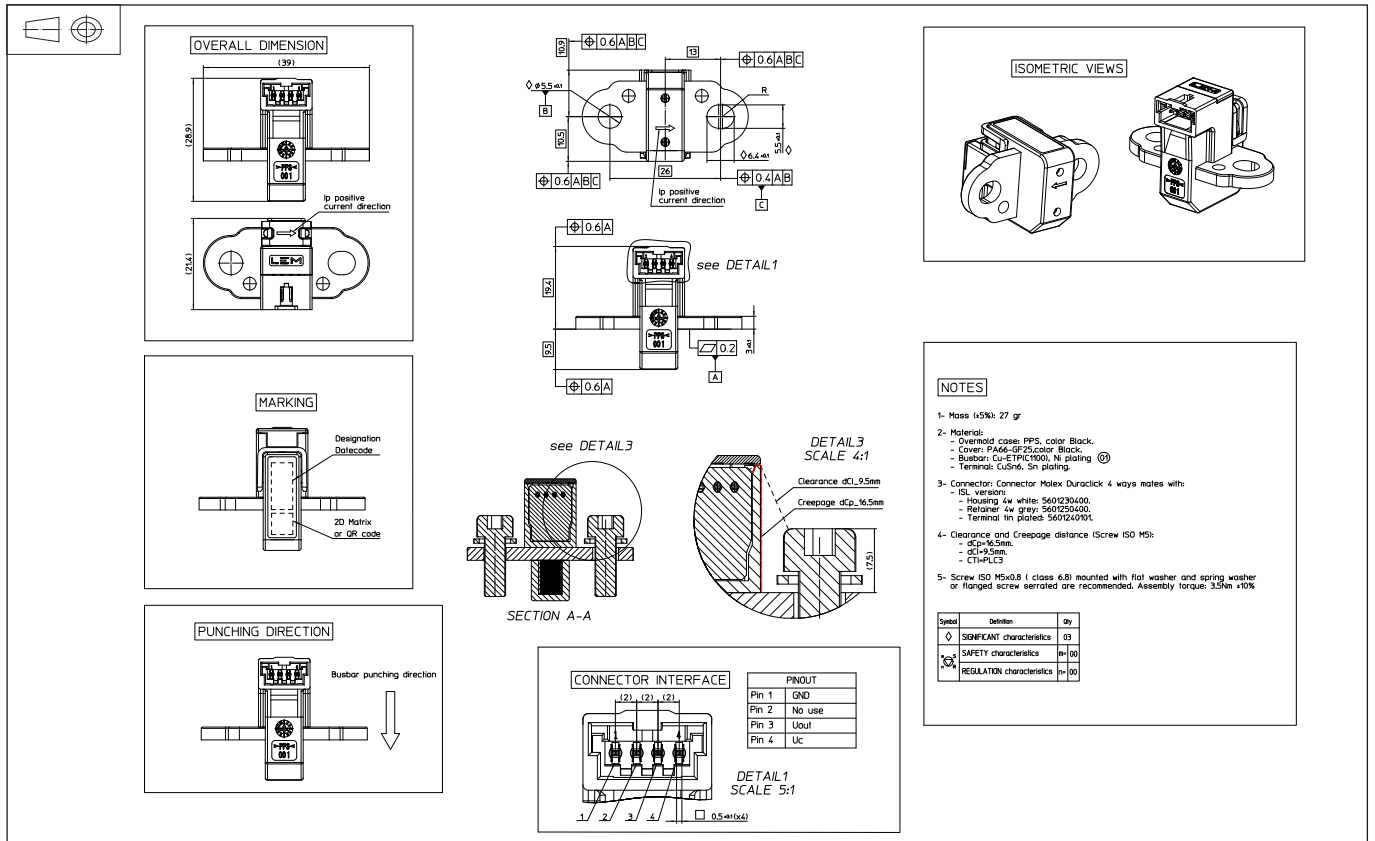


Fig. 1: Principle of the open loop transducer.

Dimensions (in mm)

Mechanical characteristics

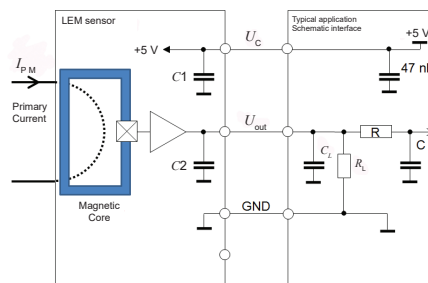
- Refer to Outline Drawing.

Mounting recommendation

- Assembly refer to Outline Drawing.

Remark

- $U_{out} > U_O$ when I_p flows in the positive direction (see arrow on drawing).

System architecture (example)


$C_C < 100$ nF EMC protection (optional)
 RC Low pass filter (optional)

Absolute ratings (not operating)

| Parameter | Symbol | Unit | Specification | | | Conditions |
|--|----------------------|------|---------------|---------|-----|-------------------------------|
| | | | Min | Typical | Max | |
| Maximum supply voltage | $U_{C\max}$ | V | -14 | | 14 | Continuous, not operating |
| Ambient storage temperature | $T_{A\text{st}}$ | °C | -40 | | 125 | |
| Electrostatic discharge voltage (HBM - Human Body Model) | $U_{\text{ESD HBM}}$ | kV | | | 8 | |
| RMS voltage for AC insulation test | U_d | kV | | | 4.7 | 50 Hz, 1 min, IEC 60664 part1 |
| Creepage distance | d_{Cp} | mm | 16.5 | | | |
| Clearance | d_{Cl} | mm | 9.5 | | | |
| Comparative tracking index | CTI | - | PLC3 | | | |
| Maximum output current | $I_{\text{out max}}$ | mA | -10 | | 10 | |
| Maximum output voltage | $U_{\text{out max}}$ | V | -14 | | 14 | |
| Insulation resistance | R_{INS} | MΩ | 500 | | | 1000 V DC |

Operating characteristics in nominal range (I_{PN})

| Parameter | Symbol | Unit | Specification | | | Conditions |
|--|---------------------|-------|--|---------|------|--|
| | | | Min | Typical | Max | |
| Electrical Data | | | | | | |
| Supply voltage | U_C | V | 4.75 | 5 | 5.25 | |
| Ambient operating temperature | T_A | °C | -40 | | 125 | |
| Output voltage (Analog) ¹⁾ | U_{out} | V | $U_{\text{out}} = (U_C / 5) \times (U_O + S \times I_P)$ | | | |
| Offset voltage | U_O | V | | 2.5 | | @ $U_C = 5\text{ V}$ |
| Current consumption | I_C | mA | | 15 | | @ $U_C = 5\text{ V}$, @ $T_A = 25\text{ °C}$, @ $I_P = 0\text{ A}$ |
| Load resistance | R_L | KΩ | 10 | | | |
| Output internal resistance | R_{out} | Ω | | 1 | 10 | |
| Performance Data | | | | | | |
| Ratiometricity error | ϵ_r | % | | ±0.3 | | @ $T_A = 25\text{ °C}$ |
| Sensitivity error | ϵ_S | % | | ±1 | | @ $T_A = 25\text{ °C}$, @ $U_C = 5\text{ V}$ |
| Electrical offset voltage | U_{OE} | mV | | ±3 | | @ $T_A = 25\text{ °C}$, @ $U_C = 5\text{ V}$ |
| Magnetic offset voltage | U_{OM} | mV | | ±1 | | @ $T_A = 25\text{ °C}$, @ $U_C = 5\text{ V}$ |
| Average temperature coefficient of U_{OE} | TCU_{OEAV} | mV/°C | | ±0.04 | | @ $-40\text{ °C} < T_A < 125\text{ °C}$ |
| Average temperature coefficient of S | TCS_{AV} | %/°C | -0.03 | ±0.01 | 0.03 | @ $-40\text{ °C} < T_A < 125\text{ °C}$ |
| Linearity error | ϵ_L | | | ±1 | | @ $U_C = 5\text{ V}$, @ $T_A = 25\text{ °C}$ |
| Frequency bandwidth ²⁾ | BW | Hz | | 35 | | @ -3 dB |
| Peak-to-peak noise voltage | $U_{\text{no pp}}$ | mV | | 10 | | @ DC to 1 MHz |
| Output RMS noise voltage | U_{no} | mV | | 1.5 | | @ DC to 1 MHz |
| Start-up time | t_{start} | ms | | | 1 | |
| Settling time after overloads | t_s | ms | | | 10 | |

Notes: ¹⁾ The output voltage U_{out} is fully ratiometric. The offset and sensitivity are dependent on the supply voltage U_C relative to the following formula:

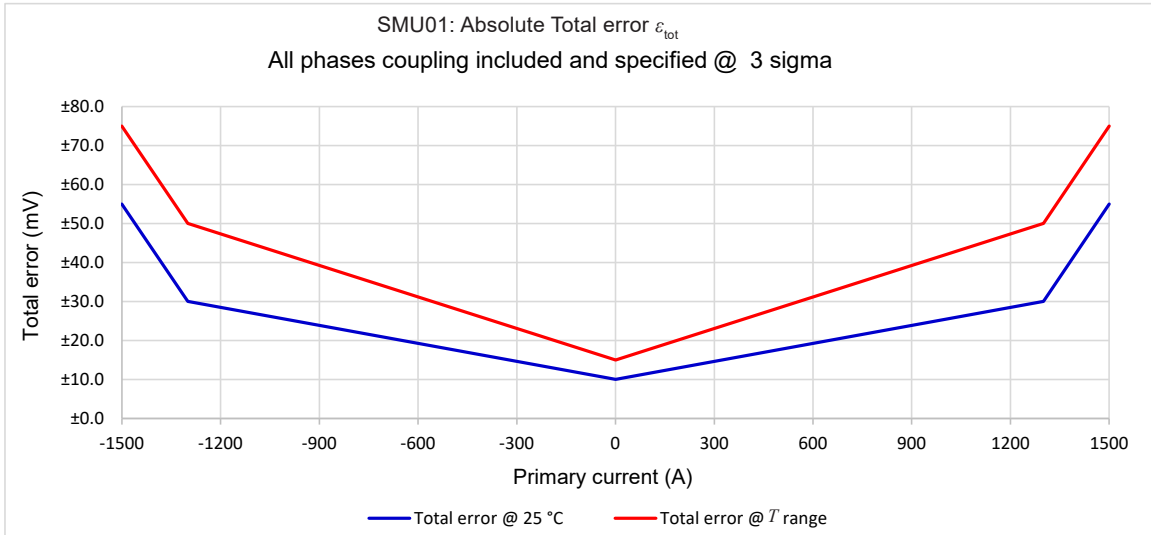
$$I_P = \left(\frac{5}{U_C} \times U_{\text{out}} - U_O \right) \times \frac{1}{S} \text{ with } S \text{ in (V/A)}$$

²⁾ Primary current frequencies must be limited in order to avoid excessive heating of the busbar, magnetic core and the ASIC (see feature paragraph in page 1/9).

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| Parameter | Symbol | Unit | Specification | | | Conditions |
|----------------------------------|----------|------|---------------|---------|------|---------------|
| | | | Min | Typical | Max | |
| Electrical Data | | | | | | |
| Primary current, measuring range | I_{PM} | A | -1500 | | 1500 | |
| Sensitivity | S | mV/A | | 1.33 | | @ $U_c = 5 V$ |

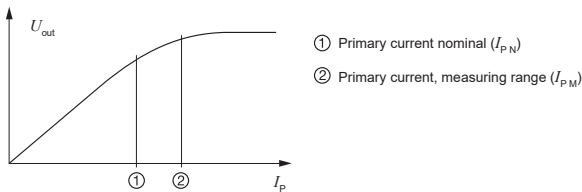
Total error



| Primary current (A) | Total error $T = 25\text{ °C}, U_c = 5\text{ V}$ | | Total error $-40\text{ °C} \leq T \leq 125\text{ °C}, U_c = 5\text{ V}$ | |
|------------------------|---|--------|--|--------|
| | (mV) | (%) | (mV) | (%) |
| -1500 | ±55 | 2.75 % | ±75 | 3.75 % |
| -1300 | ±30 | 1.50 % | ±50 | 2.50 % |
| 0 | ±10 | 0.50 % | ±15 | 0.75 % |
| -1300 | ±30 | 1.50 % | ±50 | 2.50 % |
| -1500 | ±55 | 2.75 % | ±75 | 3.75 % |

PERFORMANCES PARAMETERS DEFINITIONS

Primary current definition:



Definition of typical, minimum and maximum values:

Minimum and maximum values for specified limiting and safety conditions have to be understood as such as values shown in “typical” graphs. On the other hand, measured values are part of a statistical distribution that can be specified by an interval with upper and lower limits and a probability for measured values to lie within this interval. Unless otherwise stated (e.g. “100 % tested”), the LEM definition for such intervals designated with “min” and “max” is that the probability for values of samples to lie in this interval is 99.73 %. For a normal (Gaussian) distribution, this corresponds to an interval between -3 sigma and +3 sigma. If “typical” values are not obviously mean or average values, those values are defined to delimit intervals with a probability of 68.27 %, corresponding to an interval between -sigma and +sigma for a normal distribution. Typical, minimum and maximum values are determined during the initial characterization of a product.

Output noise voltage:

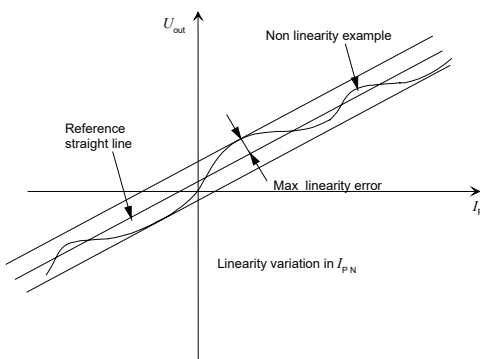
The output voltage noise is the result of the noise floor of the Hall elements and the linear amplifier.

Magnetic offset:

The magnetic offset is the consequence of an any current on the primary side. It’s defined after a stated excursion of primary current.

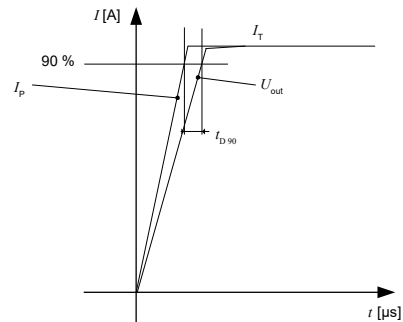
Linearity:

The maximum positive or negative discrepancy with a reference straight line $U_{out} = f(I_p)$.
Unit: linearity (%) expressed with full scale of I_{pN} .



Response time (delay time) t_{D90} :

The time between the primary current signal (I_{pN}) and the output signal reach at 90 % of its final value.



Sensitivity:

The transducer’s sensitivity S is the slope of the straight line $U_{out} = f(I_p)$, it must establish the relation:

$$U_{out}(I_p) = U_c / 5 (S \times I_p + U_o)$$

Offset with temperature:

The error of the offset in the operating temperature is the variation of the offset in the temperature considered with the initial offset at 25 °C.

The offset variation I_{OT} is a maximum variation the offset in the temperature range:

$$I_{OT} = I_{OE} \text{ max} - I_{OE} \text{ min}$$

The offset drift TCI_{OEAV} is the I_{OT} value divided by the temperature range.

Sensitivity with temperature:

The error of the sensitivity in the operating temperature is the relative variation of sensitivity with the temperature considered with the initial offset at 25 °C.

The sensitivity variation S_T is the maximum variation (in ppm or %) of the sensitivity in the temperature range:
 $S_T = (\text{Sensitivity max} - \text{Sensitivity min}) / \text{Sensitivity at } 25 \text{ °C}$.

The sensitivity drift TCS_{AV} is the S_T value divided by the temperature range. Deeper and detailed info available is our LEM technical sales offices (www.lem.com).

Offset voltage @ $I_p = 0 \text{ A}$:

The offset voltage is the output voltage when the primary current is zero. The ideal value of U_o is $U_c / 2$. So, the difference of $U_o - U_c / 2$ is called the total offset voltage error. This offset error can be attributed to the electrical offset (due to the resolution of the ASIC quiescent voltage trimming), the magnetic offset, the thermal drift and the thermal hysteresis. Deeper and detailed info available is our LEM technical sales offices (www.lem.com).

Environmental test specifications:

Refer to LEM GROUP test plan laboratory CO.11.11.515.0 with “Tracking_Test Plan_Auto” sheet.

Validation test specifications

| Name | Standard | Condition |
|---|------------------------------------|---|
| ENVIRONMENTAL TESTS | | |
| Ageing 85 °C /85 % RH | JESD 22-A101 (03/2009) | 85 °C/85 % RH; Duration = 1000 h; Power supply 5 V ; primary current 0 A; Monitoring output 1 time/hr |
| Low temperature operating endurance | ISO 16750-4 § 5.1.1.2 (04/2010) | -40 °C, 24 h; Power supply 5 V Monitoring: 2 times/hr |
| High temperature operating endurance | ISO 16750-4 § 5.1.2.2 (04/2010) | Temperature 125 °C; 96 h; power supply 5 V Monitoring 2 times/hr |
| Humidity heat, cyclic test: Test 2 Composite temperature/humidity cyclic test | ISO 16750-4 § 5.6.2.3 (04/2010) | Temperature range -10 °C/ +65 °C, 93 % RH Duration = 240 h (10 cycles) |
| Thermal shock | ISO 16750-4 § 5.3.2 (04/2010) | Temperature range -40 °C& 125 °C, 300 cycles; 40 min/40 min, no power supply |
| Random Vibration | ISO 16750-3 § 4.1.2.4 | Monitoring U_c and U_{out} is mandatory, Temperature -40/125 °C, 10 to 1000 HZ, 27.1 m/s ² , 8 H/axis |
| Mechanical Shocks | ISO 16750-3 § 4.2.2 | Operating mode: 3.2 Pulse shape: half sine, 500 m/s ² , 6 ms 10 shocks per direction (total 60) |
| Free Fall | ISO 16750-3 § 4.3 | Height = 1 m 3 axes, 2 directions by axis, Operating mode: 1.1 |
| Cross section checking on PCBA | IPC-A-610G: 2017 Class 3 | IPC-TM-650 2.1.1F:2015 |
| Whisker checking on PCBA | Refer to JESD201-A (04/2010) | Refer to JESD22-A121A (04/2010) Class 2 |
| INSULATION TESTS | | |
| Dielectric withstand voltage | ISO 16750-2 § 4.11 (11/2012) | 4.7 kV test voltage, time = 60 s, No dielectric breakdown, no flash-over, functional after test |
| Insulation test | ISO 16750-2 § 4.12 (11/2012) | 1000 V DC, time = 60 s, $R_{isolation} \geq 500 \text{ M}\Omega$ Minimum |
| EMC TESTS | | |
| Immunity to Electrostatic Discharges (Handling of devices) | ISO 10605 (07/2008) | Discharge module: 150 pF/330 Ω Contact discharges: $\pm 4 \text{ kV}$, Air discharges: $\pm 8 \text{ kV}$ U_c = NO power supply, Criteria C |
| Immunity to Radiated disturbances (ALSE) | ISO 11452-2 (2019) | Power supply: 5 V $f = 400 \text{ MHz}$ to 1 GHz; Level = 100 V/m (CW, AM 80 %) $f = 0.8 \text{ GHz}$ to 1GHz; Level = 70 V/m (PM1) $f = 1 \text{ GHz}$ to 1.2 GHz; Level = 70 V/m (CW, PM1) $f = 1.2 \text{ GHz}$ to 1.4 GHz; Level = 70 V/m (CW, PM2) $f = 1.4 \text{ GHz}$ to 2 GHz; Level = 70 V/m (CW, PM1) Criteria: A Acceptance @ 2500 mV $\pm 100 \text{ mV}$ |
| Immunity to Conducted disturbances (BCI) | ISO 11452-4 (12/2011) | Level = see Annex E Fig. & Table E.1 (Test Level II) $f = 1 \text{ MHz}$ to 400 MHz Criteria: A Acceptance @ 2500 mV $\pm 100 \text{ mV}$ |
| Emission Radiated (ALSE) | CISPR 25 §6.5 (2016) | Table 7, Class 5 by default $f = 150 \text{ kHz}$ to 2.5 GHz Load simulator will be provided (R&D) |